

Analysis of small-angle scattering data using model fitting and Bayesian regularization

Andreas Haahr Larsen

Post Doc

Niels Bohr Institute & Dep. Biology

Bayes for Scattering,

May 6th 2019

UNIVERSITY OF COPENHAGEN

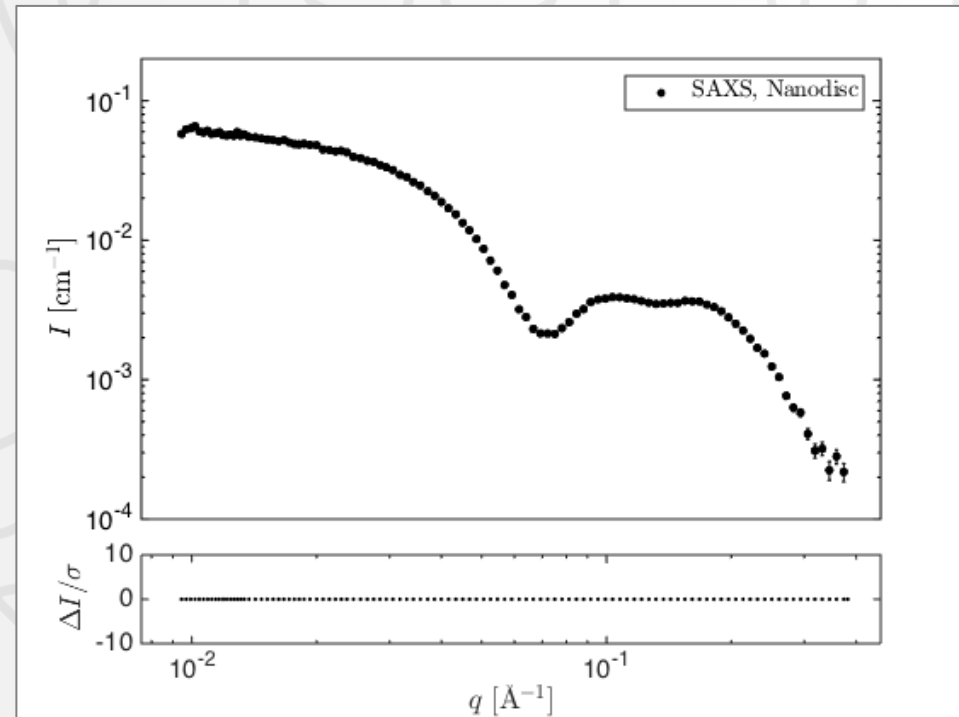
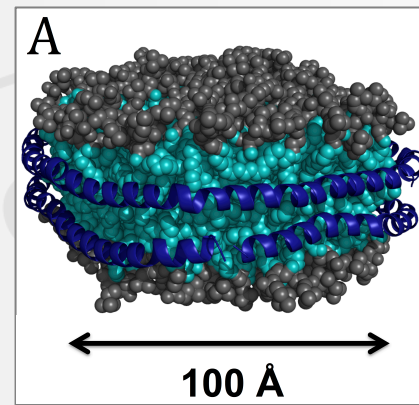


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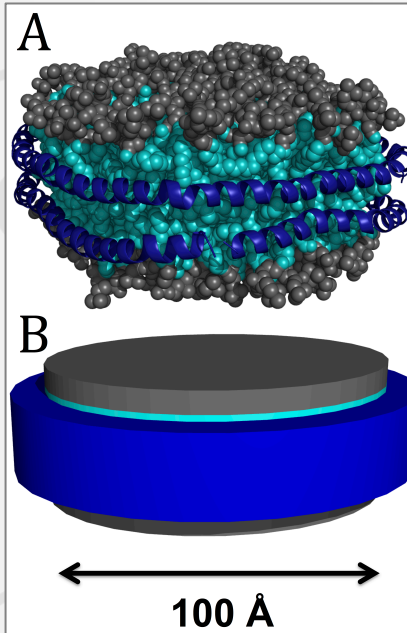
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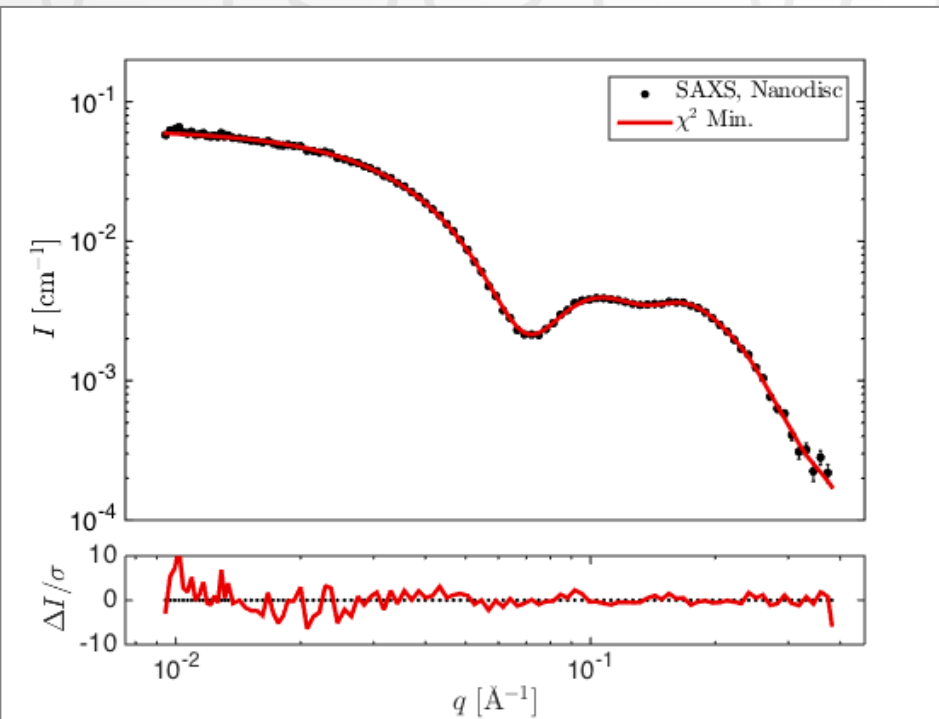
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Model parameter	χ^2 minimization
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ε	1.3 (4.5)
A (\AA^2)	76 (19)
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Goodness of fit, χ_r^2	6.26
Goodness of fit, Cmap	$C = 10, N = 106$ $P(C \geq 10 N) = 9.2\%$



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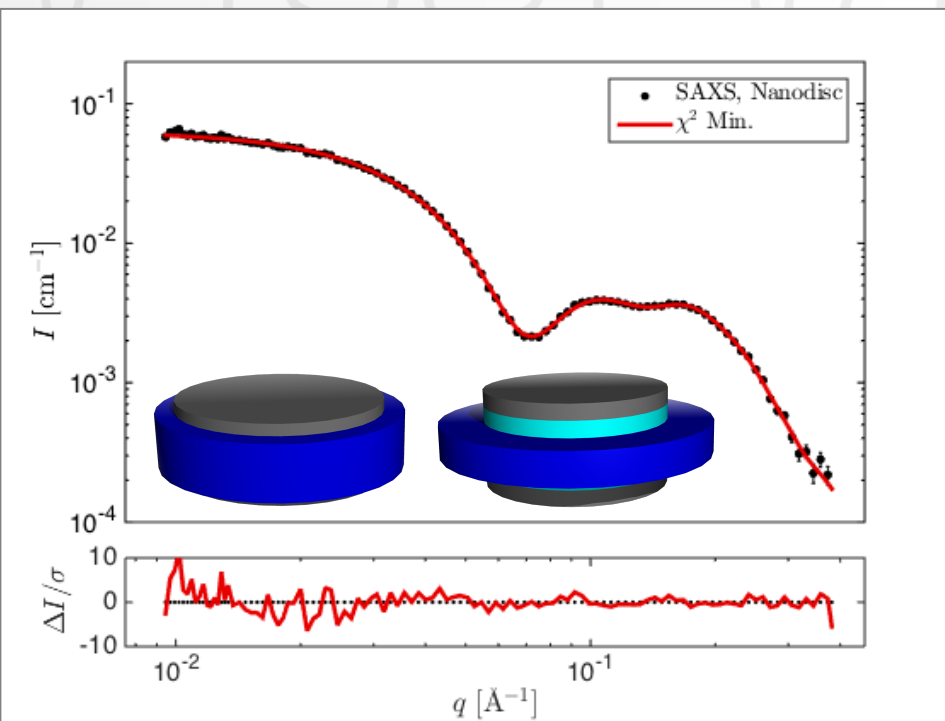
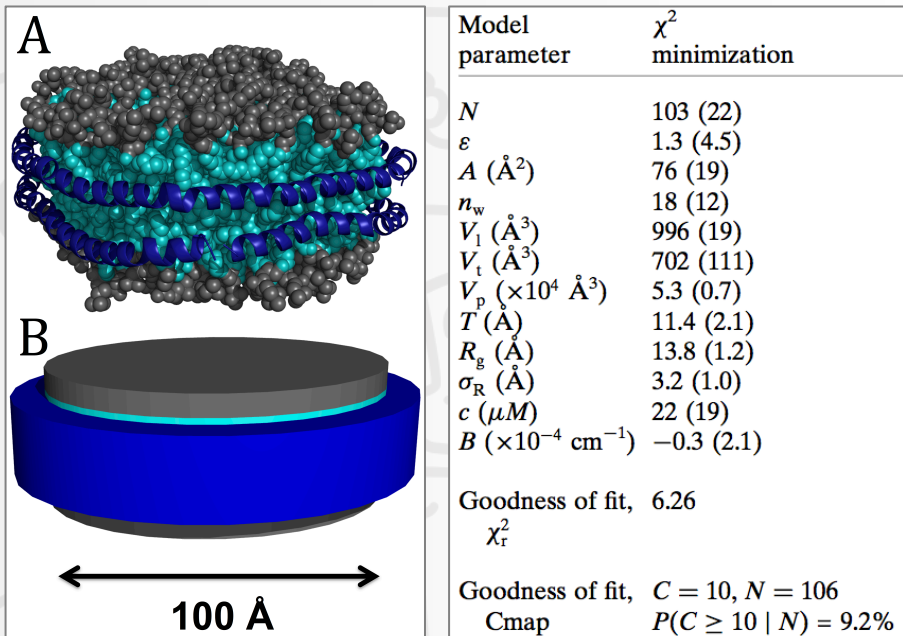
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Problem:

- Several possible parameters, some unphysical
- How to select the most probable set of parameters



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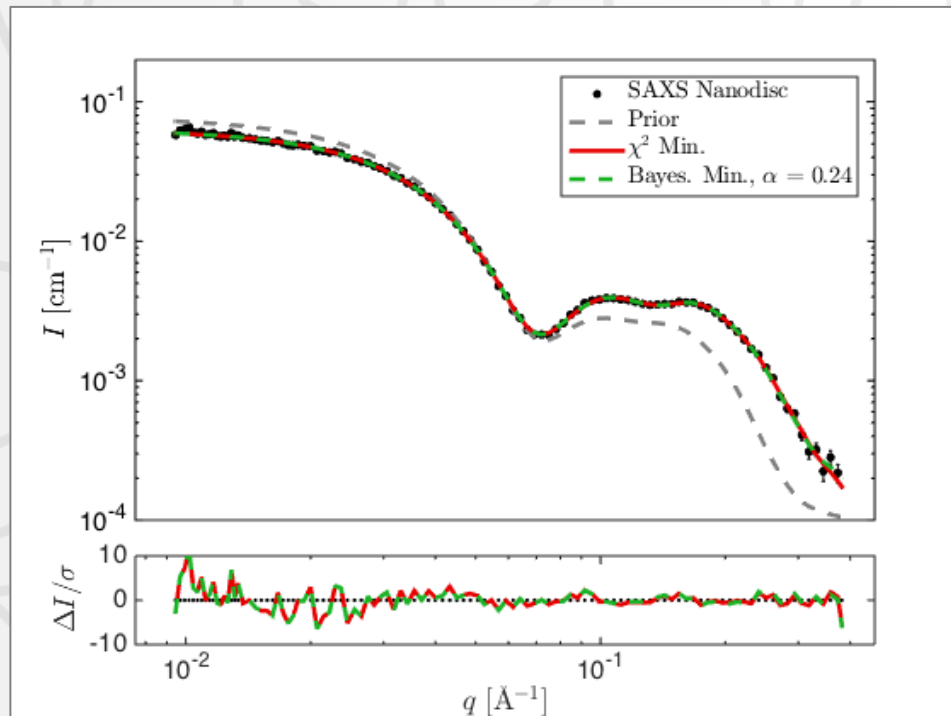
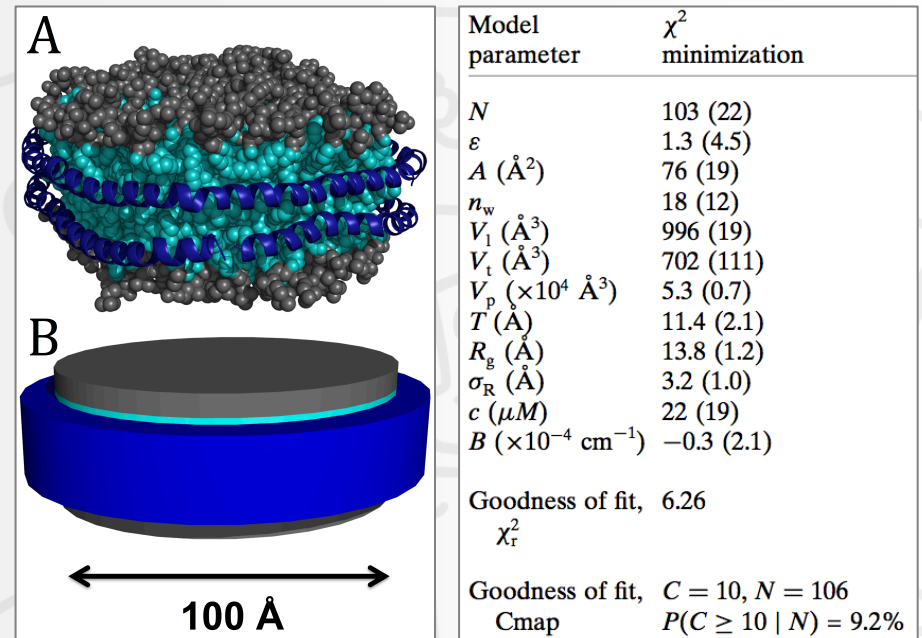


Problem:

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Solution:

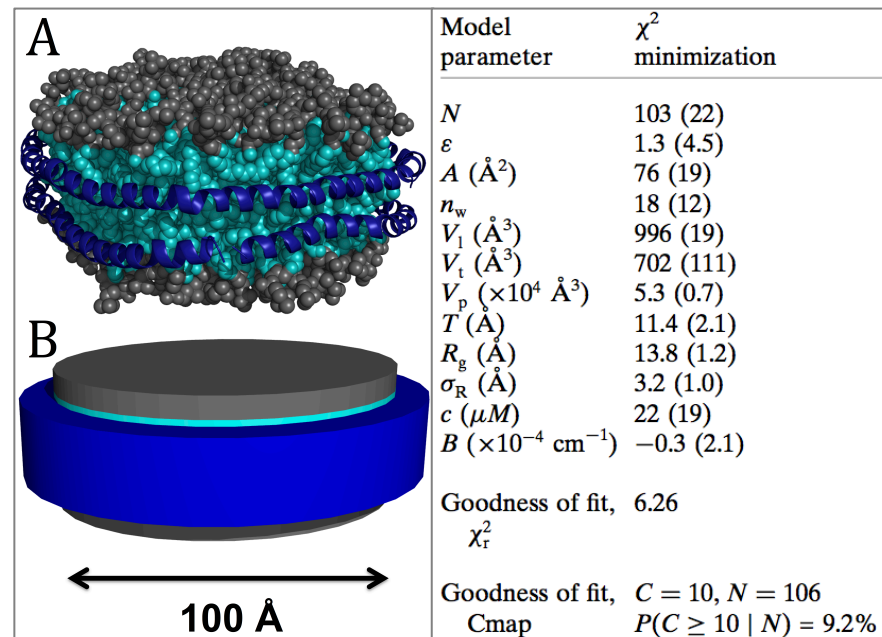
Analysis with Bayesian regularization



Strategies to select the most probable set of parameters

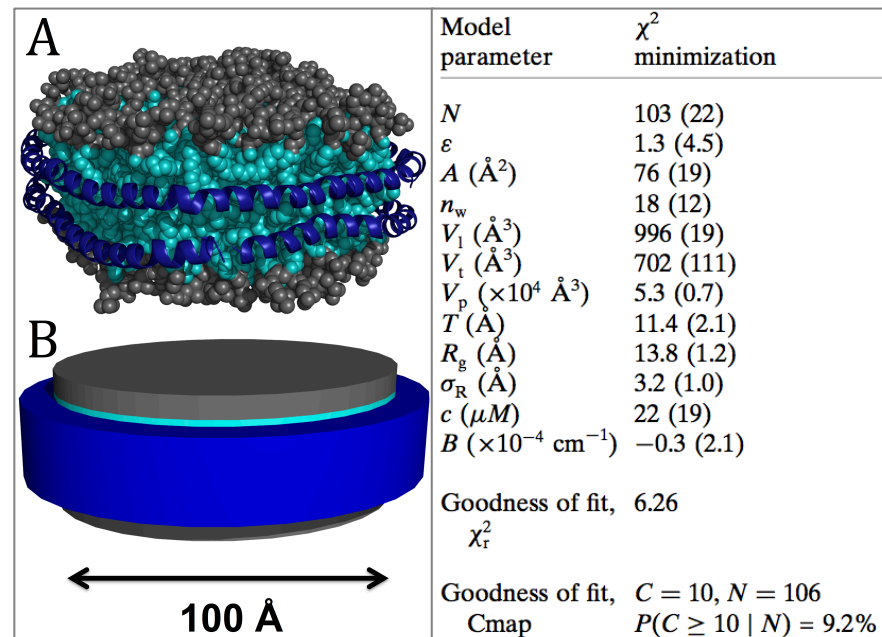
1. Molecular constraints

- reparametrisation



Strategies to select the most probable set of parameters

1. Molecular constraints
 - reparametrisation
2. Fix parameters

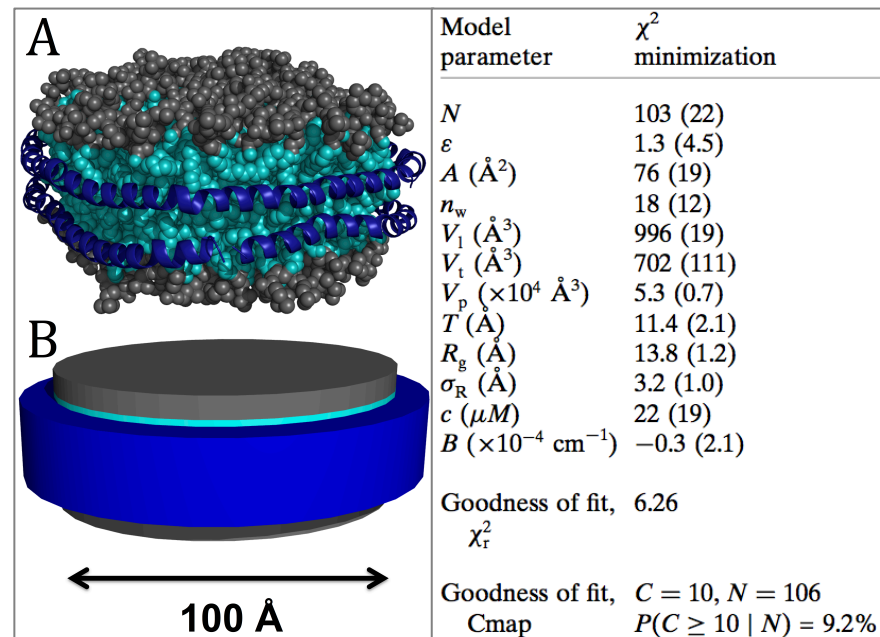


Strategies to select the most probable set of parameters

1. Molecular constraints
 - reparametrisation
2. Fix parameters
3. Limit allowed parameter interval

Uniform prior

$$p(\kappa) = \begin{cases} s & \text{if } a \leq \kappa \leq b, \\ 0 & \text{otherwise,} \end{cases}$$



SasView

Will It Fit?

CRY SOL

FOXS

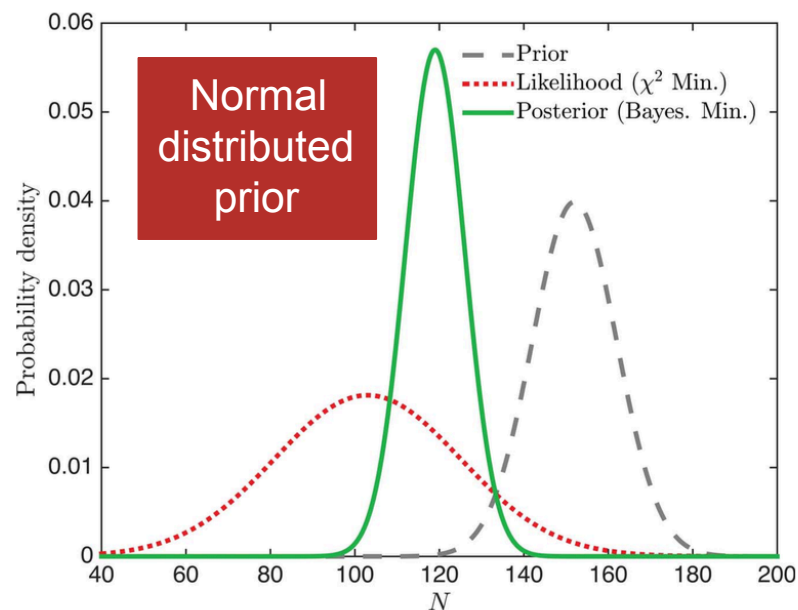
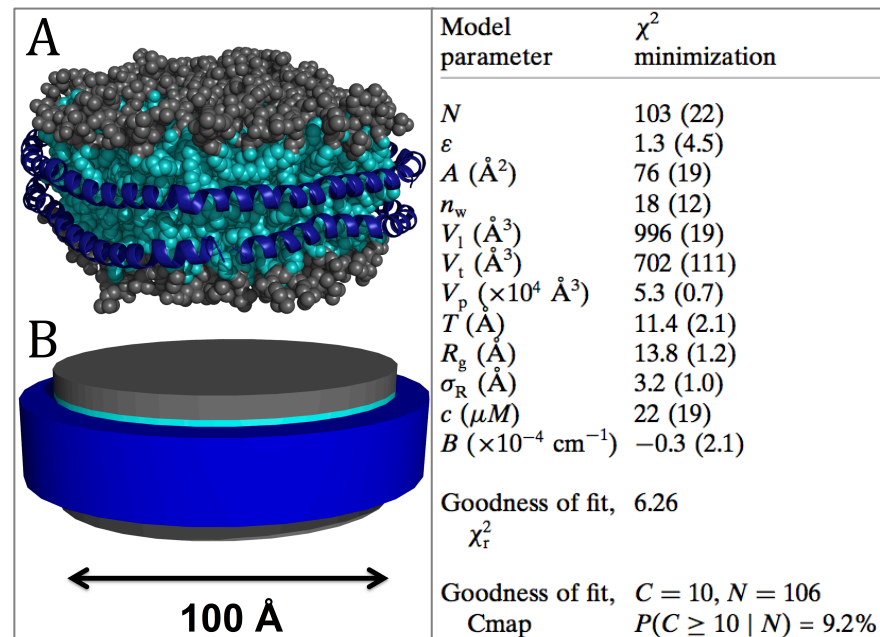
Strategies to select the most probable set of parameters

1. **Molecular constraints**
 - reparametrisation
2. **Fix parameters**
3. **Limit allowed parameter interval**

Uniform prior

$$p(\kappa) = \begin{cases} s & \text{if } a \leq \kappa \leq b, \\ 0 & \text{otherwise,} \end{cases}$$

4. **Bayesian regularisation**



Strategies to select the most probable set of parameters

1. **Molecular constraints**
 - reparametrisation
2. **Fix parameters**
3. **Limit allowed parameter interval**

Uniform prior

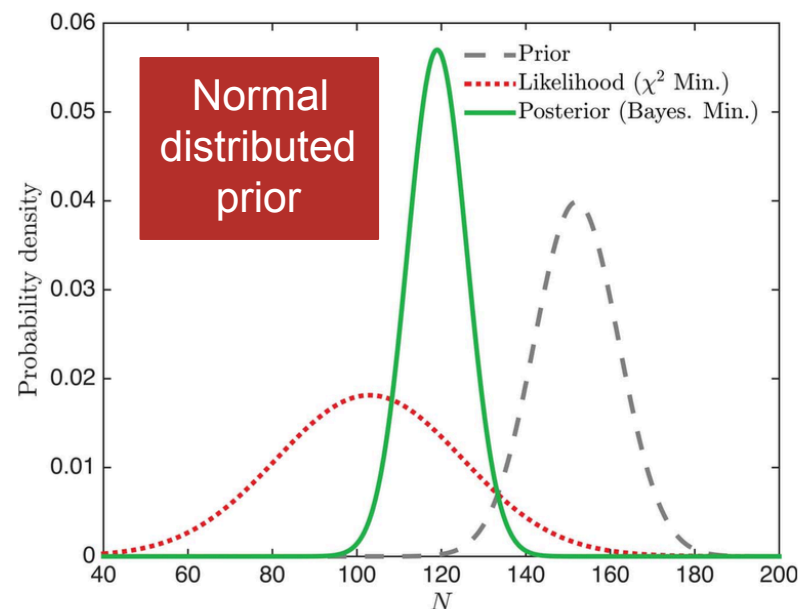
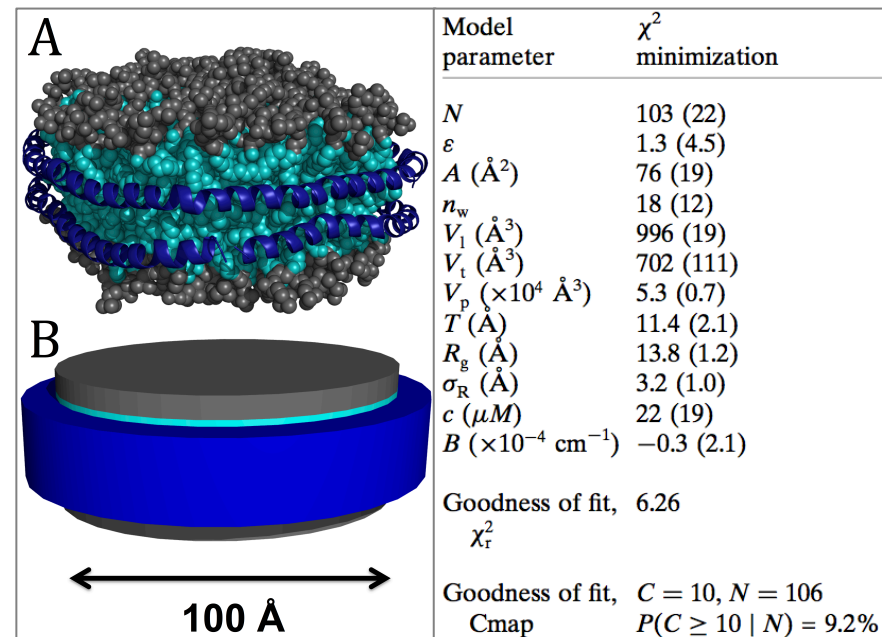
$$p(\kappa) = \begin{cases} s & \text{if } a \leq \kappa \leq b, \\ 0 & \text{otherwise,} \end{cases}$$

4. Bayesian regularisation

not regularised:
$$\chi^2(\mathbf{p}) = \sum_{i=1}^N \frac{[I_i^{\text{exp}} - I_i^{\text{th}}(\mathbf{p})]^2}{\sigma_i^2}$$

regularised:
$$Q(\mathbf{p}) = \chi^2(\mathbf{p}) + \alpha S(\mathbf{p}).$$

prior:
$$S(\mathbf{p}) = \sum_{k=1}^K \frac{(p_k - \mu_k)^2}{\delta p_k^2}$$



Challenges in Bayesian regularization

1. **Determining α :**

$$-2 \log \underbrace{[P(D, \alpha | H)]}_{\text{evidence}} = Q(\mathbf{p}) + \log(\Gamma) + 2 \log(\alpha)$$

Probability

Challenges in Bayesian regularization

1. **Determining α :**

$$\begin{array}{c}
 \textit{Probability} \quad : \quad \chi^2(\mathbf{p}) + \alpha S(\mathbf{p}), \\
 \downarrow \\
 -2 \log[P(D, \alpha | H)] = \underbrace{Q(\mathbf{p})}_{\textit{evidence}} + \log(\Gamma) + 2 \log(\alpha)
 \end{array}$$

Challenges in Bayesian regularization

1. Determining α :

$$-2 \log[P(D, \alpha | H)] = \underbrace{Q(\mathbf{p})}_{\text{evidence}} + \underbrace{\log(\Gamma) + 2 \log(\alpha)}_{\text{Occam term}}$$

Probability : $\chi^2(\mathbf{p}) + \alpha S(\mathbf{p})$

Occam's razor:

Choose the simplest explanation

Challenges in Bayesian regularization

1. **Determining α :**

$$-2 \log[P(D, \alpha | H)] = \underbrace{Q(\mathbf{p})}_{\text{evidence}} + \underbrace{\log(\Gamma)}_{\text{Occam term}} + \underbrace{2 \log(\alpha)}_{\text{prior for } \alpha}$$

$\chi^2(\mathbf{p}) + \alpha S(\mathbf{p})$

Probability

Occam's razor:

Choose the simplest explanation

Challenges in Bayesian regularization

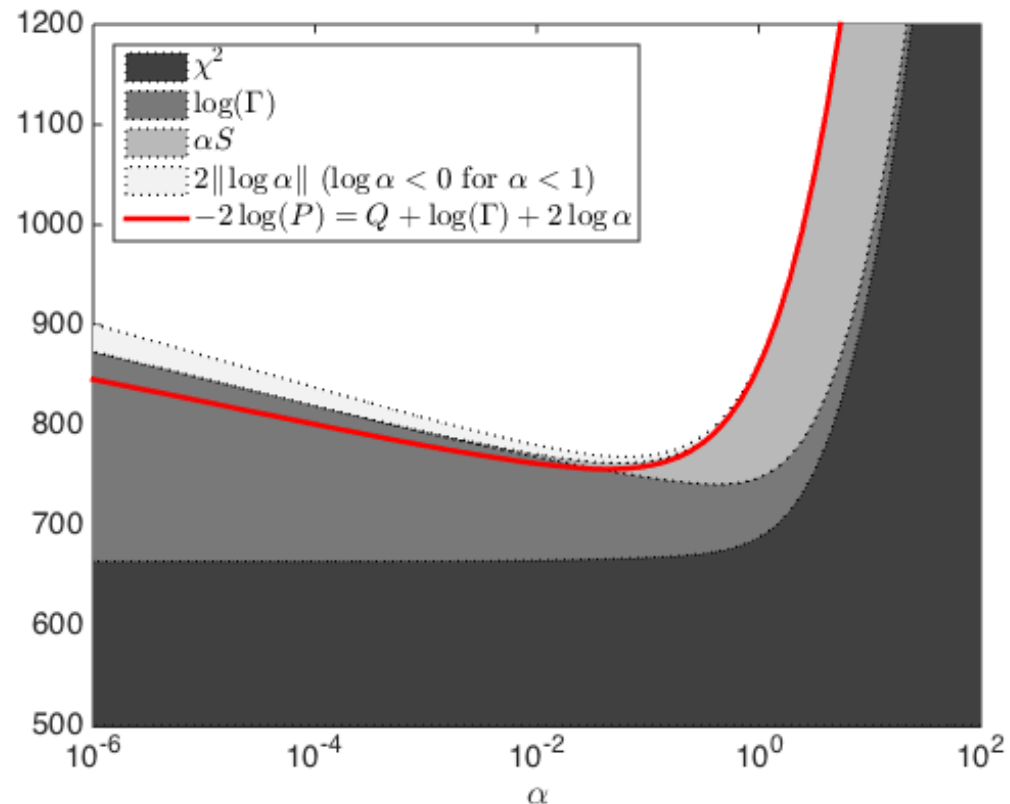
1. Determining α :

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Occam's razor:

Choose the simplest explanation
Here: same as prior (large α)



Challenges in Bayesian regularization

1. Determining α :

$$-2 \log[P(D, \alpha | H)] = \underbrace{\chi^2(\mathbf{p})}_{\text{evidence}} + \underbrace{\log(\Gamma)}_{\text{Occam term}} + \underbrace{2 \log(\alpha)}_{\text{prior for } \alpha}$$

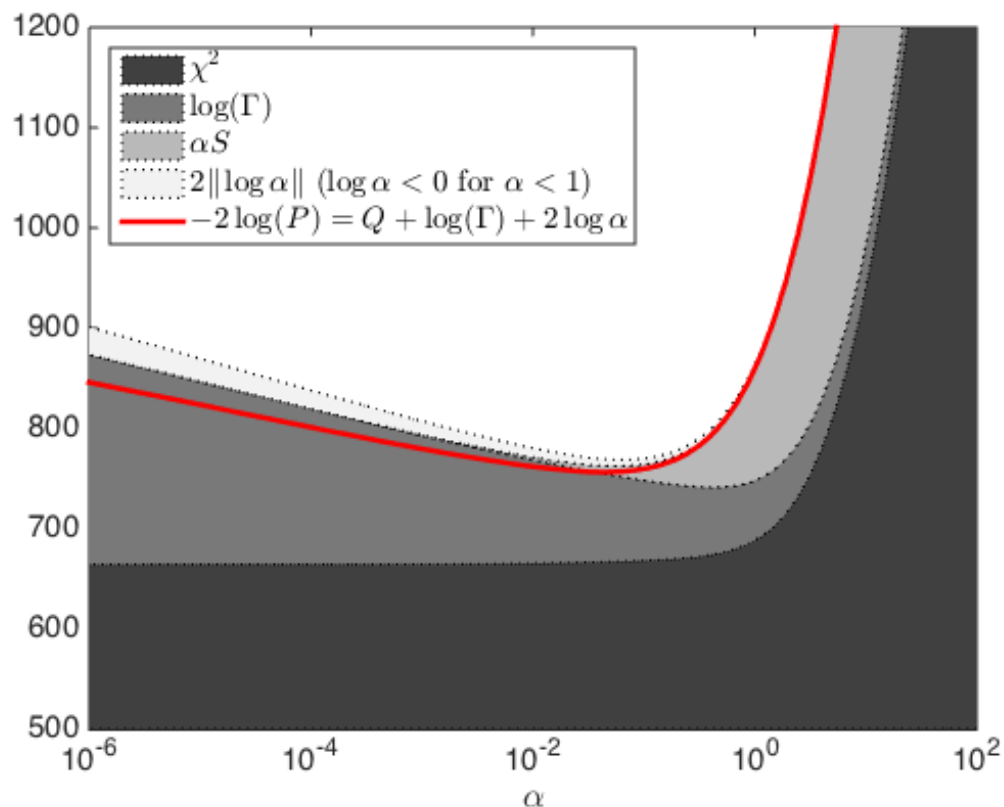
Probability : $\chi^2(\mathbf{p}) + \alpha S(\mathbf{p})$, *prior for α*

Occam's razor:

Choose the simplest explanation
Here: same as prior (large α)

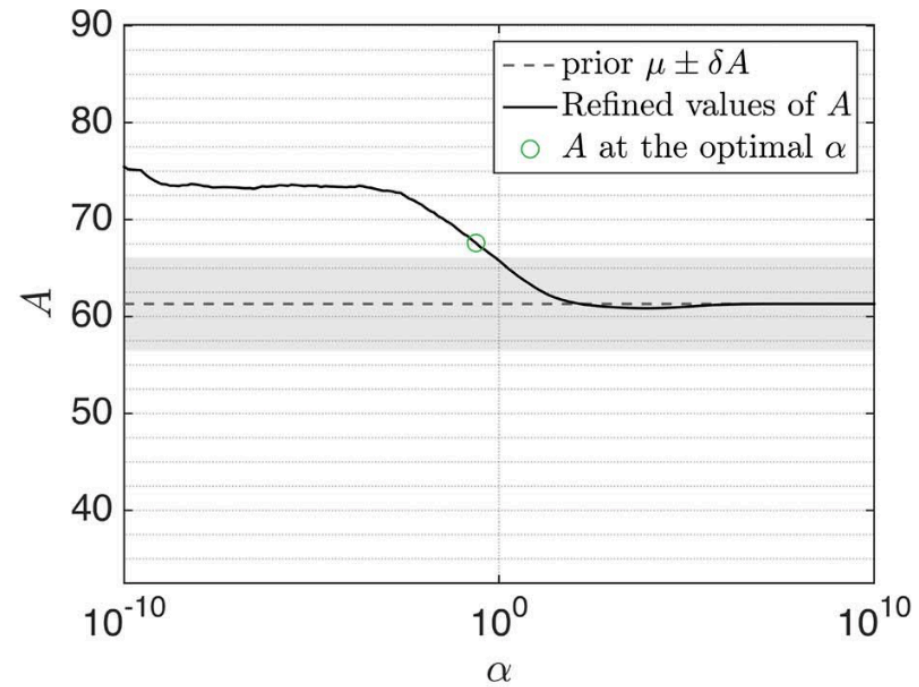
2. Choose prior

- Case 1: From experiment
- Case 2: General knowledge
- Case 3: Unknown



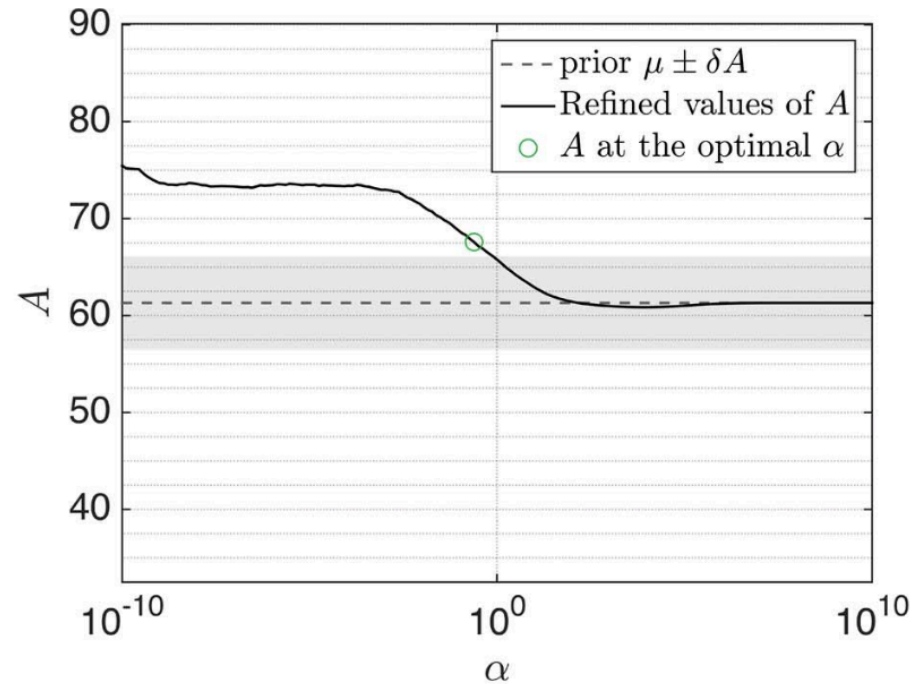
Benefits of Bayesian regularization

1. Most probable solution found



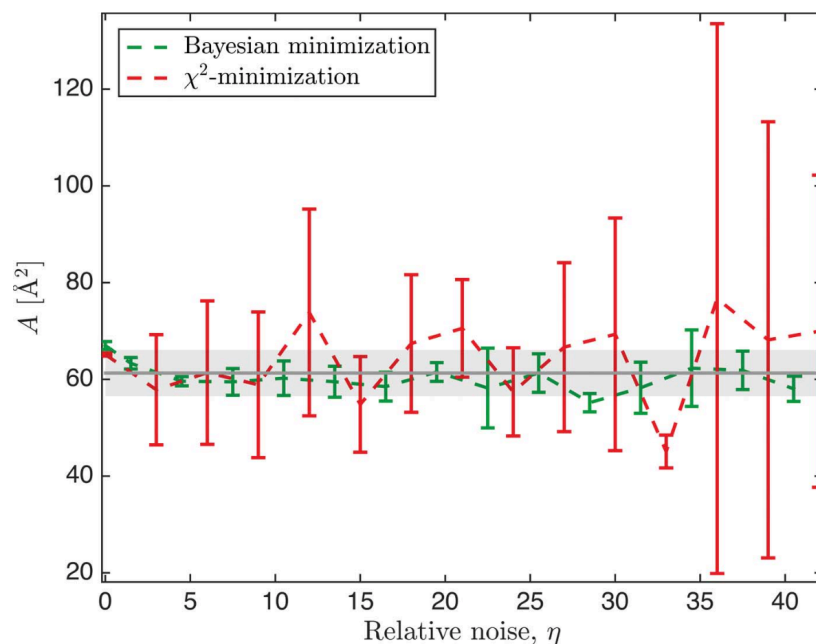
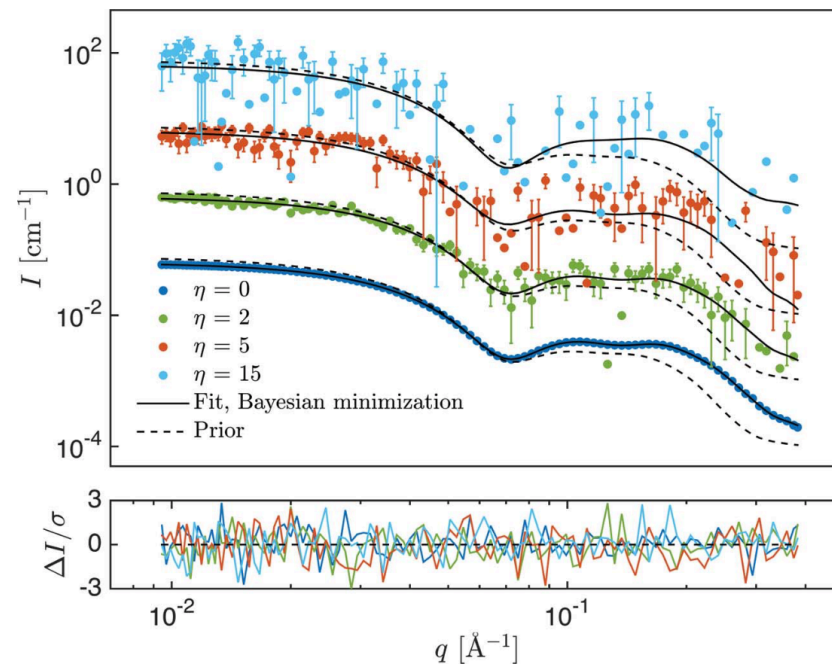
Benefits of Bayesian regularization

1. Most probable solution found
2. Better error estimation



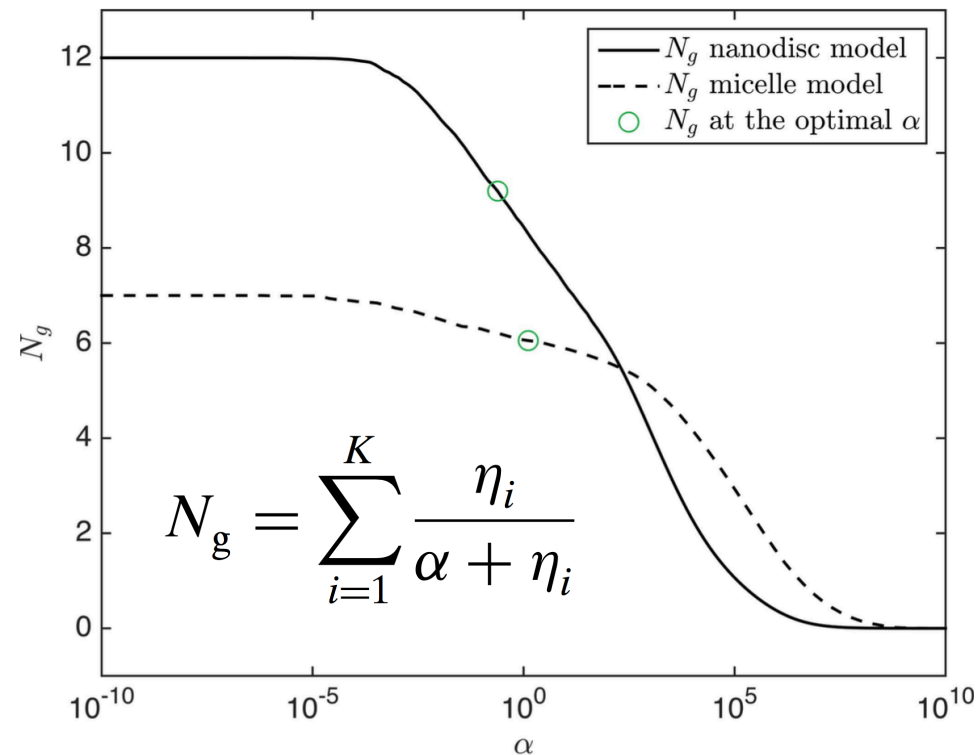
Benefits of Bayesian regularization

1. Most probable solution found
2. Better error estimation
3. Stable solution for noisy data

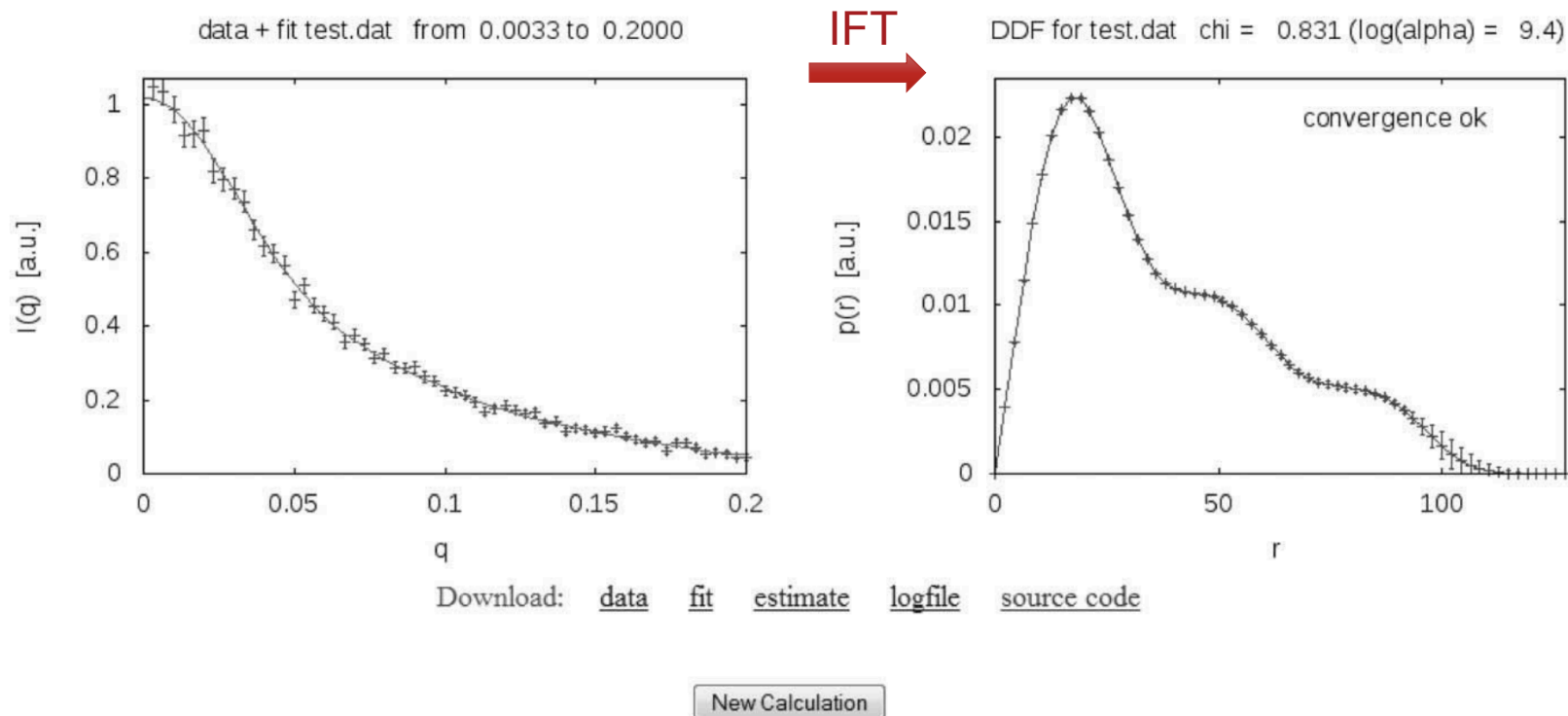


Benefits of Bayesian regularization

1. **Most probable solution found**
2. **Better error determination**
3. **Stable solution for noisy data**
4. **Measure for information**
 - include prior knowledge
 - depends on model



Bayes for Indirect Fourier Transformation



$$Q(\mathbf{p}) = \chi^2(\mathbf{p}) + \underbrace{\alpha S(\mathbf{p})}_{\text{smoothness constraint}}$$

www.bayesapp.org

Hansen, 2000, *J. Appl. Cryst.*, 33, 1415-1421

Hansen, 2014, *J. Appl. Cryst.*, 33, 1469-1471

Perspectives

- Include in SasView, WilltFit and similar programs
- Combining SAXS and SANS
- Other techniques, e.g. reflectometry

The logo for SasView, featuring the word "SasView" in a light blue, sans-serif font. The letter "V" is stylized with a blue sphere above it, resembling a data point or a particle.The logo for "Will It Fit?", consisting of the text "Will It Fit?" in white, bold, sans-serif font, set against a solid black rectangular background.

See more:

Larsen, Arleth & Hansen, 2018,
J. Appl. Cryst. 51, 1151-1161.

Acknowledgements

Co-authors/ supervisors

Lise Arleth
Steen Hansen



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Søren Roi Midtgaard

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Martin Cramer Pedersen
Reviewers



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Thank you for your attention!

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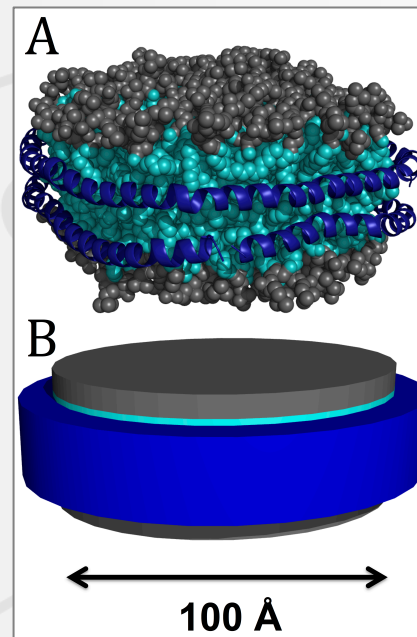
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