



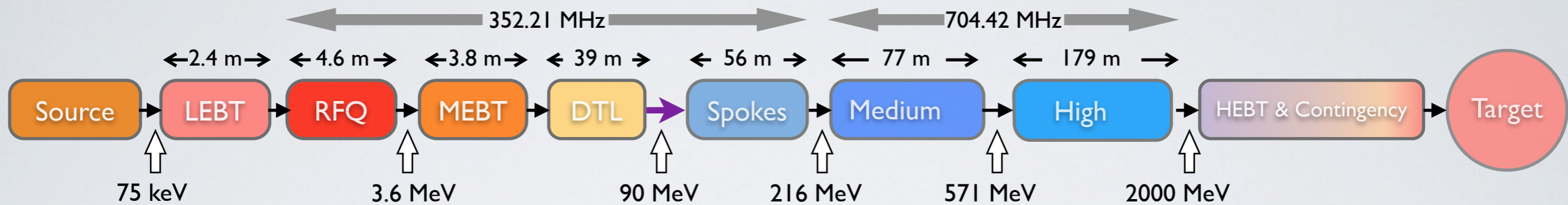
# THE ESS LINAC

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for the Accelerator physics work package

2014 May 13, Lund

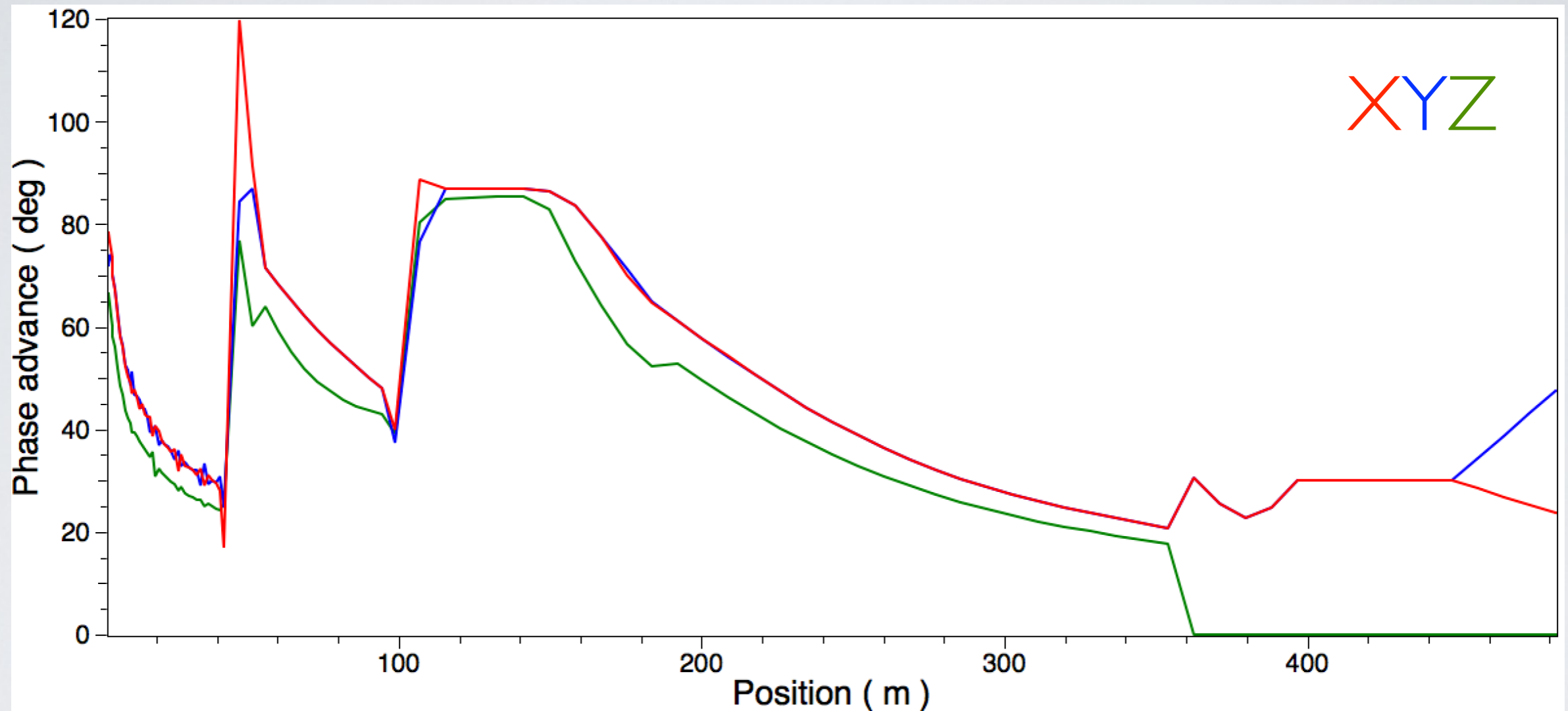


# THE ESS LINAC

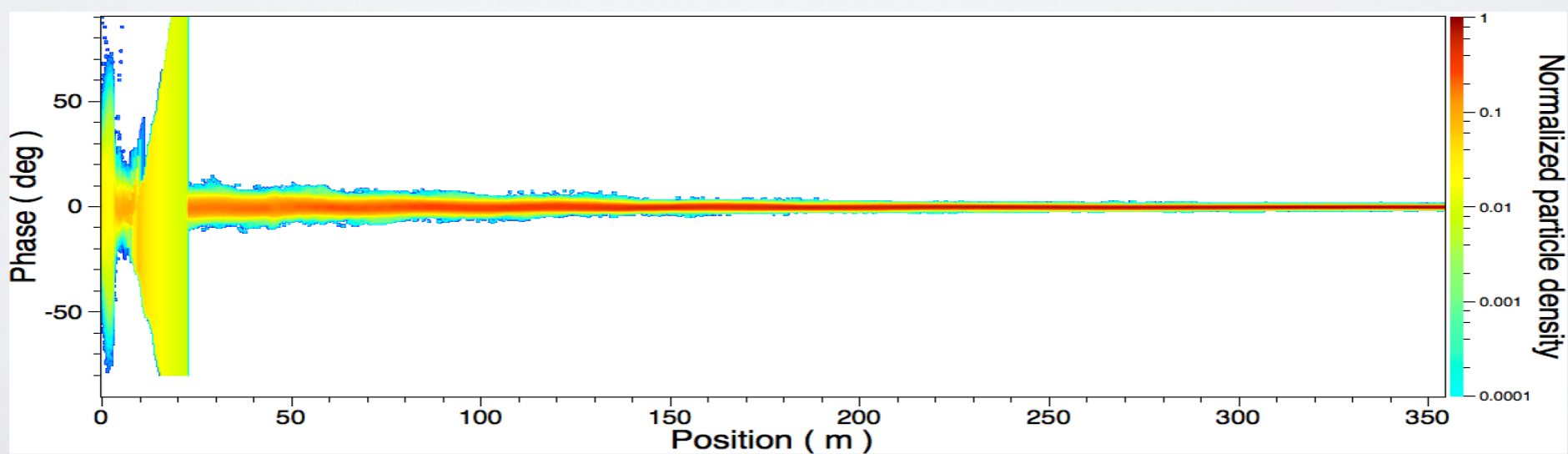
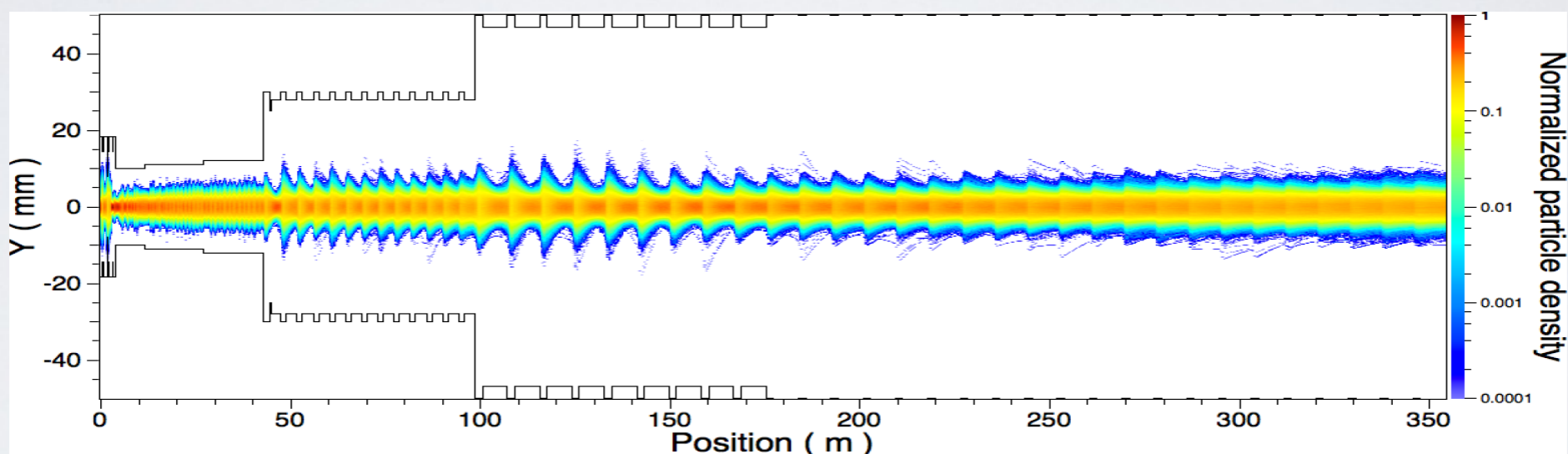
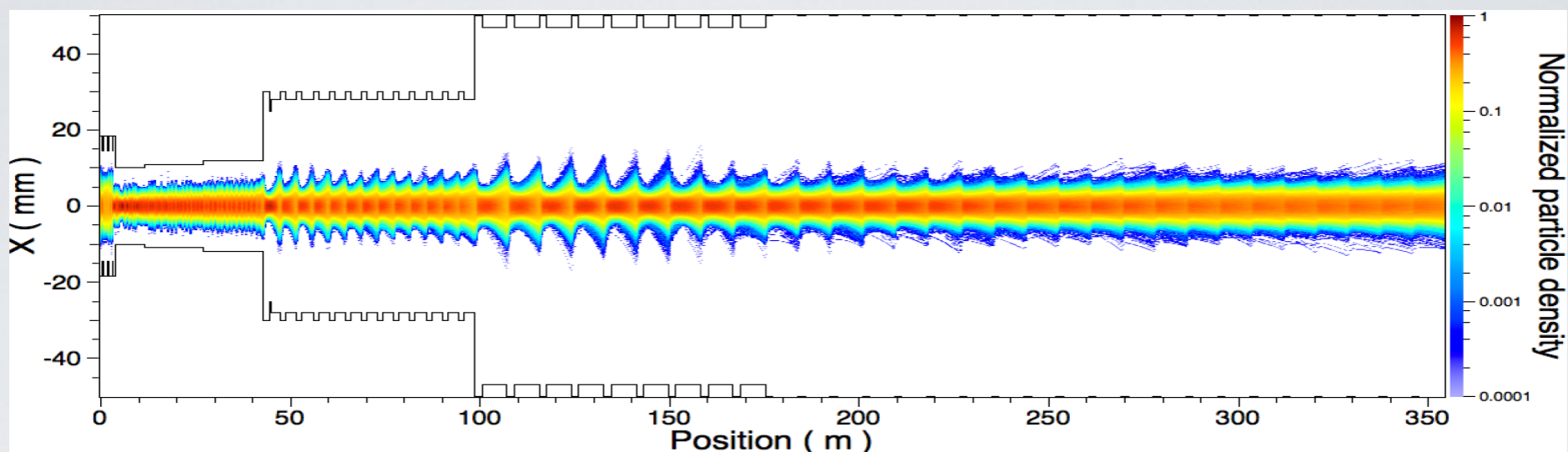


	Length (m)	W <sub>in</sub> (MeV)	F (MHz)	β Geometric	No. Sections	T (K)
LEBT	2.38	0.075	--	--	1	~300
RFQ	4.6	0.075	352.21	--	1	~300
MEBT	3.81	3.62	352.21	--	1	~300
DTL	38.9	3.62	352.21	--	5	~300
LEDP + Spoke	55.9	89.8	352.21	0.50	13	~2
Medium Beta	76.7	216.3	704.42	0.67	9	~2
High Beta	178.9	571.5	704.42	0.86	21	~2
Contingency	119.3	2000	704.42	(0.86)	14	~300 / ~2
Upgrade	59.6	2000	704.42	(0.86)	7	~300 / ~2

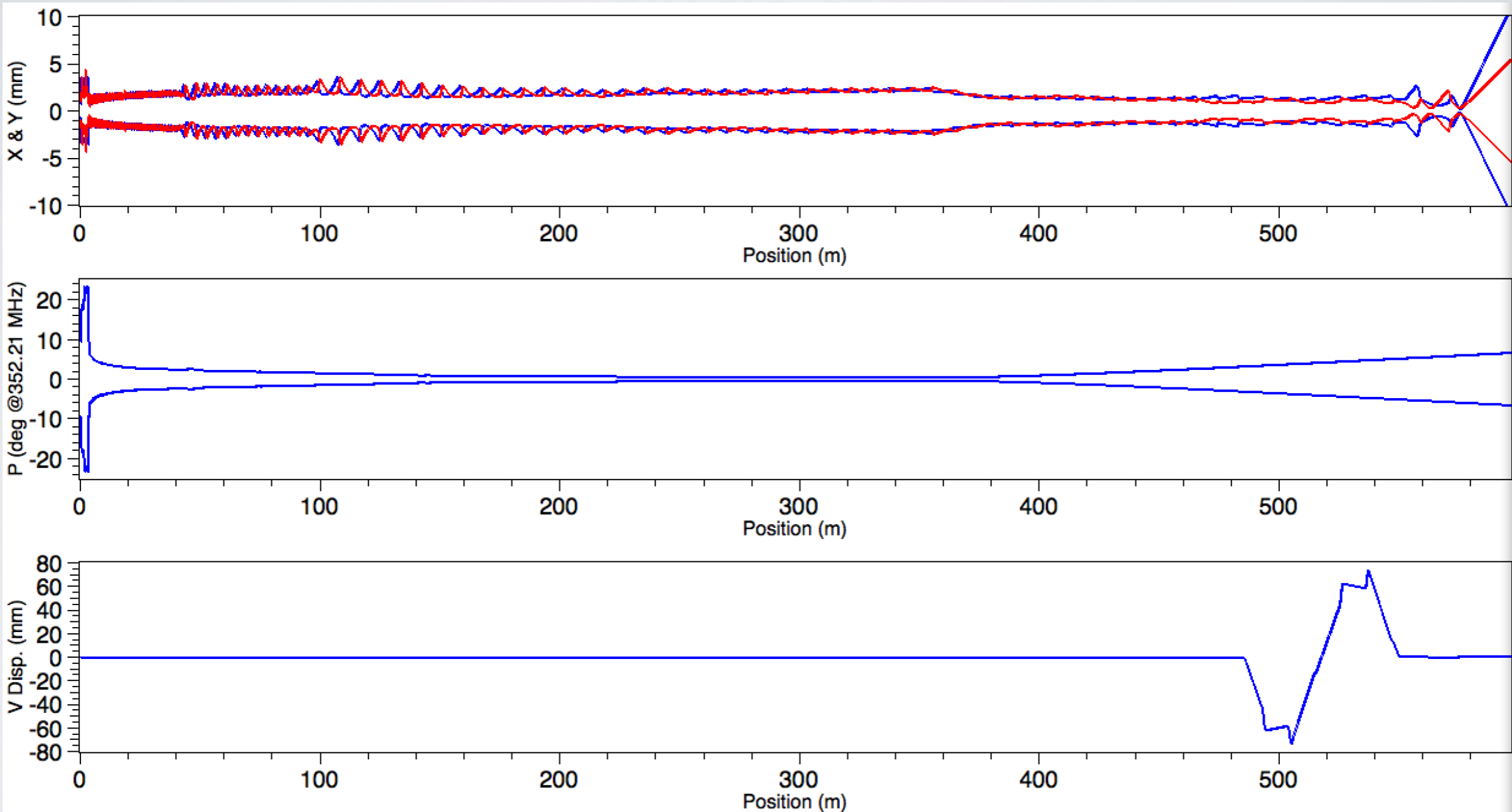
# PHASE ADVANCE @ RIGHT ENERGY



# NO ERRORS



# ENVELOPES





# APPLIED ERRORS I

- RFQ:
  - ▶ Input beam
    - ◎ Input beam position and angle
    - ◎ Input beam mismatch (alpha and beta)
  - ▶ Machining
    - ◎ Longitudinal profile of the vane
    - ◎ Transverse profile of the vane
  - ▶ Alignment and Voltage errors
    - ◎ Parallel and perpendicular vane shift
    - ◎ Parallel and perpendicular vane tilt
    - ◎ Section shift
    - ◎ Section tilt
    - ◎ Voltage jitter



# APPLIED ERRORS II

- MEBT:
  - ▶ Input beam
    - Position and angle
    - Emittances
    - Mismatch (alpha and beta)
    - Energy
    - Current



# APPLIED ERRORS III

- MEBT:
  - ▶ Quadrupoles
    - Alignment
    - Rotation around the beam axis
    - Gradient
  - ▶ Cavities
    - Alignment
    - Tilt perpendicular to beam axis
    - Field and phase set point
    - Field and phase jitter





# APPLIED ERRORS IV

- DTL:
  - ▶ PMQ
    - Alignment
    - Rotation around the beam axis
    - Gradient
  - ▶ RF
    - Field and phase error on each cell
    - Tank field and phase set point
    - Tank field and phase jitter



# APPLIED ERRORS V

- Spoke/MB/HB:
  - ▶ Quad
    - Alignment
    - Rotation around the beam axis
    - Gradient
  - ▶ Cavity
    - Alignment
    - Tilt perpendicular to beam axis
    - Field and phase set point error
    - Field and phase jitter



# APPLIED ERRORS VI

- HEBT/DogLeg/A2T
  - ▶ Quad
    - Alignment
    - Rotation around the beam axis
    - Gradient
  - ▶ Dipole
    - Alignment
    - Tilt perpendicular to beam axis
    - Field error



# ERROR STRATEGY

- 10% emittance growth per plane on top of nominal per section
- Effect of dynamic errors smaller than the rms energy/phase spread within the beam
- Optimizing the positions of steerers
- Minimizing the number of active BPMs
- Defining the transverse tolerances after setting (and using) the steering strategy



# TOLERANCES (RFQ)

<b>Input beam error</b>	<b>Alignment position</b>	0.2	mm
	<b>Alignment angle</b>	2	mrad
	<b>Twiss mismatch (</b>	10	%
	<b>Twiss mismatch (</b>	5	%
<b>Machining errors</b>	<b>Longitudinal vane profile</b>	0.02	mm
	<b>Transverse vane curvature</b>	0.02	mm
<b>Alignment error</b>	<b>Parallel and perpendicular vane shift</b>	0.03	mm
	<b>Parallel and perpendicular vane tilt</b>	0.03	mrad
	<b>Horizontal and vertical segment shift</b>	0.03	mm
	<b>Segment tilt around X and Y axis</b>	0.03	mrad
<b>Voltage error</b>	<b>Vane voltage jitter</b>	0.5	%

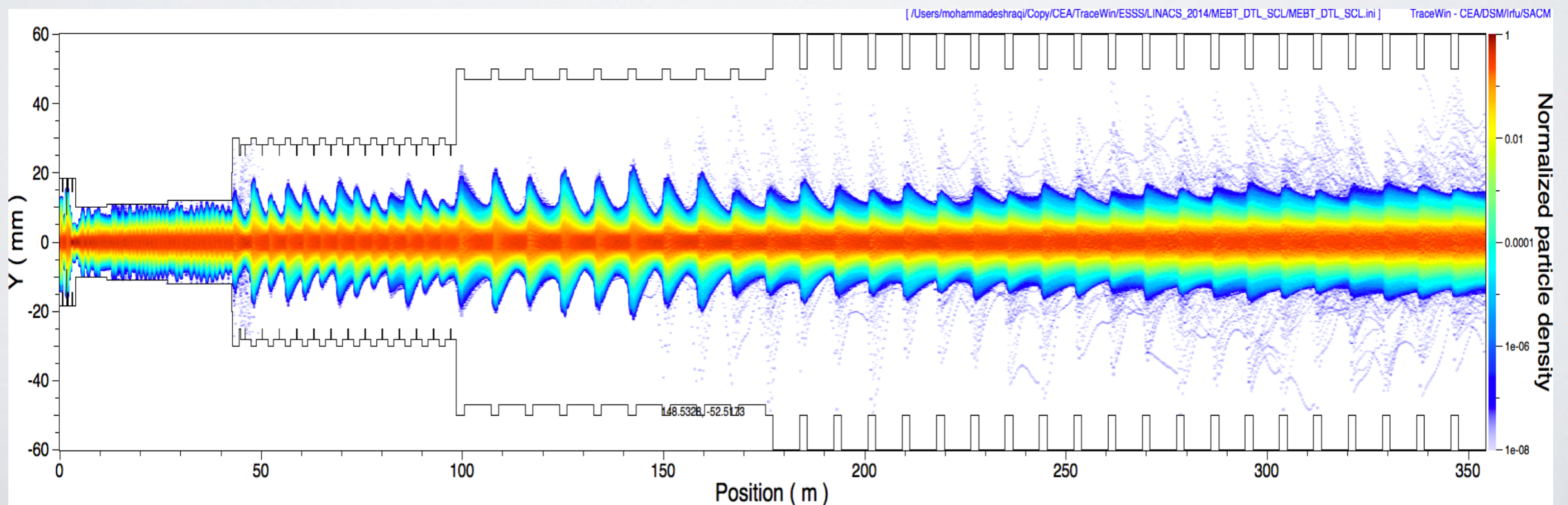
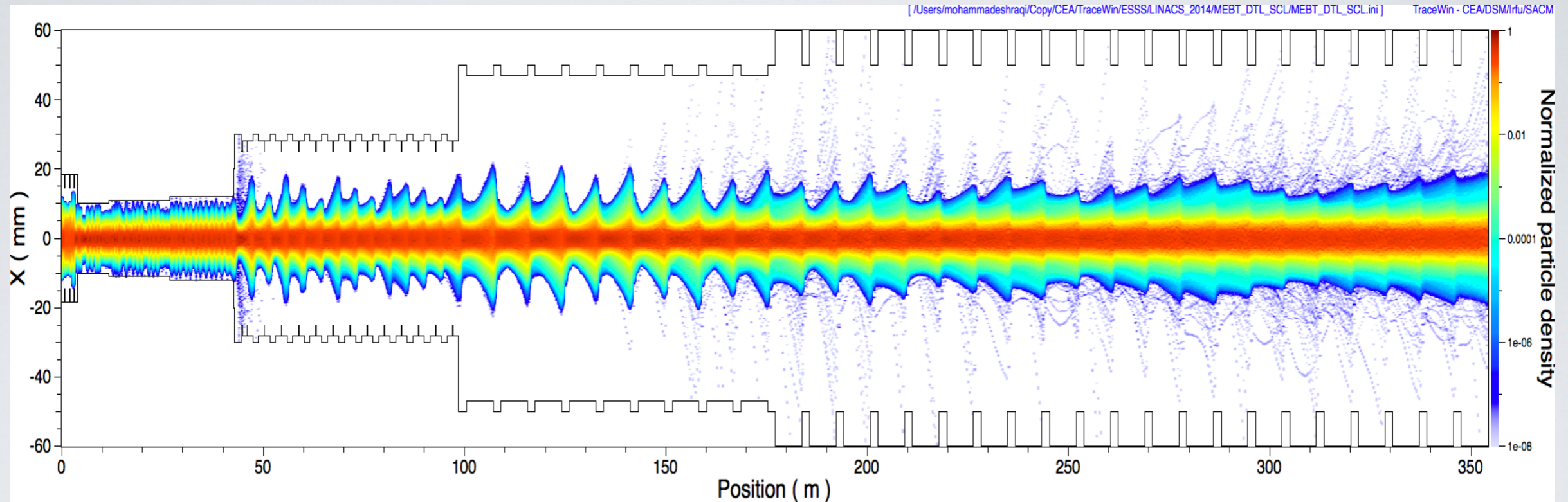


# TOLERANCES

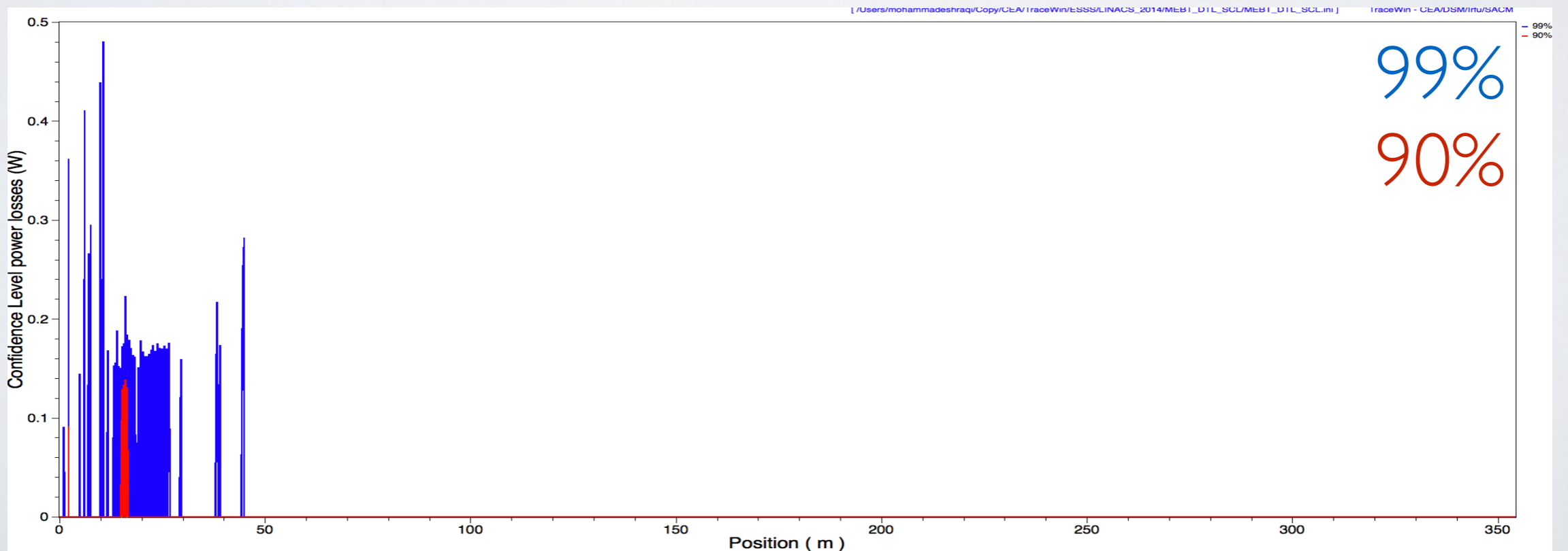
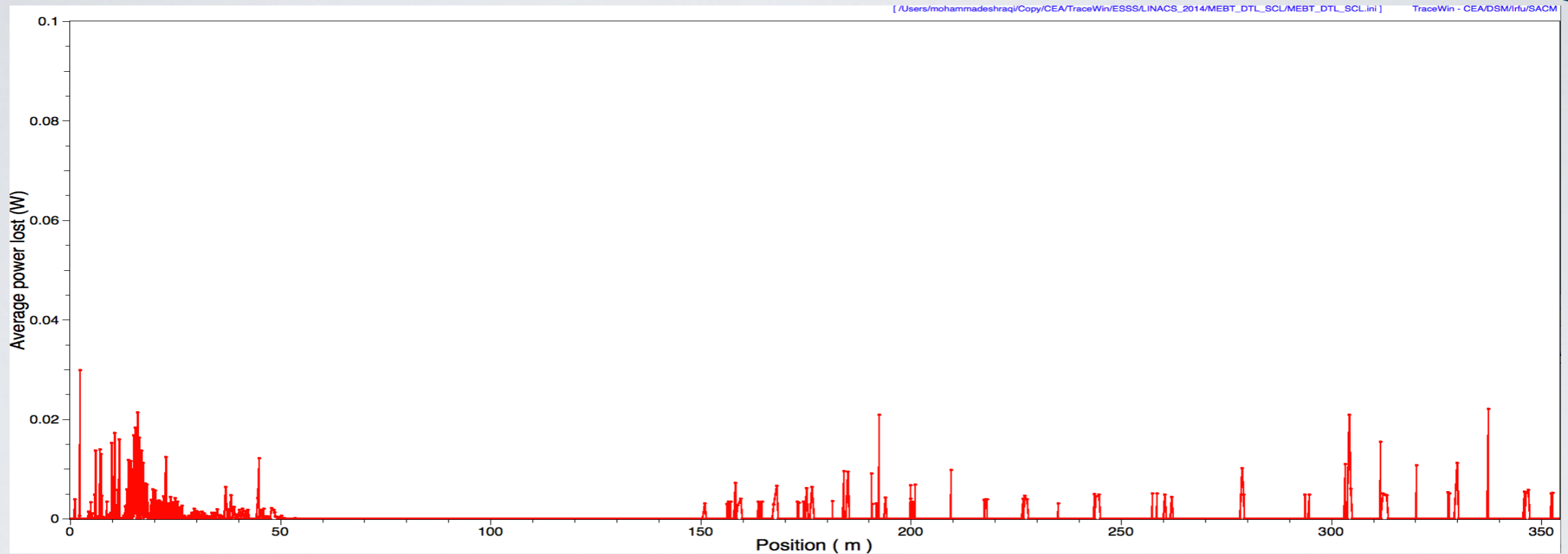
	dx (mm)	dy (mm)	dφ(°)	dx'(mrad)	dy'(mrad)	dE (%)	dEx (%)	dEy (%)	dEz (%)	mx	my	mz	dI (mA)
<b>Beam</b>	0.3	0.3	0	1	1	0.01	5	5	5	5	5	5	0.625

			dx (mm)	dy (mm)	φx (°)	φy (°)	φz (°)	dG	dφ	dE
<b>MEBT</b>	<b>Static</b>	<b>QUAD</b>	0.2	0.2	0	0	0.06	0.5	—	—
	<b>Static</b>	<b>Cavity</b>	0.5	0.5	0.115	0.115	—	—	1	1
	<b>Dynamic</b>	<b>Cavity</b>	0	0	0	0	—	—	0.1	0.1
<b>DTL</b>	<b>Static</b>	<b>QUAD</b>	0.15	0.15	0.5	0.5	0.24	0.9	—	—
	<b>Static</b>	<b>Cav_CL</b>	0	0	0	0	—	—	2	2
	<b>Static</b>	<b>Cav_TK</b>	0	0	0	0	—	—	1	1
	<b>Dyanmic</b>	<b>Cav_TK</b>	0	0	0	0	—	—	0.1	0.1
<b>Spoke MB HB</b>	<b>Static</b>	<b>Quad</b>	0.2	0.2	0	0	0.06	0.5	—	—
	<b>Static</b>	<b>Cavity</b>	1.5	1.5	0.129	0.129	—	—	1	1
	<b>Dynamic</b>	<b>Cavity</b>	0	0	0	0	0	0	0.1	0.1
<b>HEBT</b>	<b>Static</b>	<b>Quad</b>	0.2	0.2	0	0	0.06	0.5	—	—
	<b>Static</b>	<b>Dipole</b>	0.2	0.2	0	0	0.06	0.05	—	—

# RFQ TO HB ERROR RESULTS

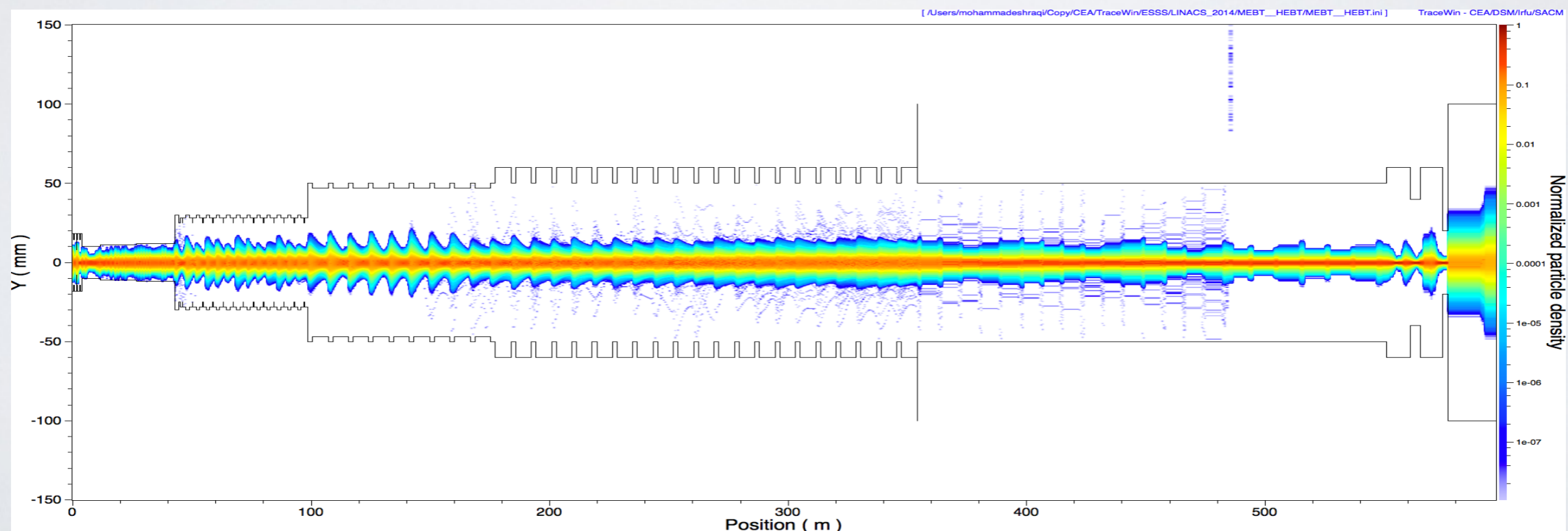
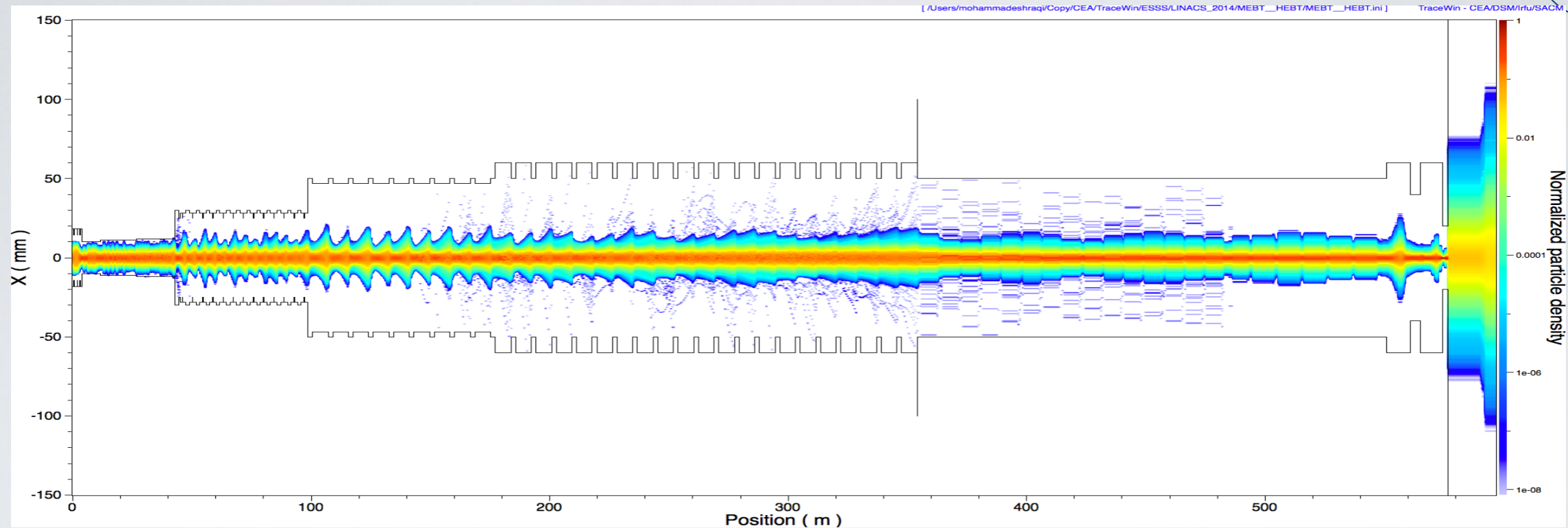


# RFQ TO HB ERROR LOSS MAPS



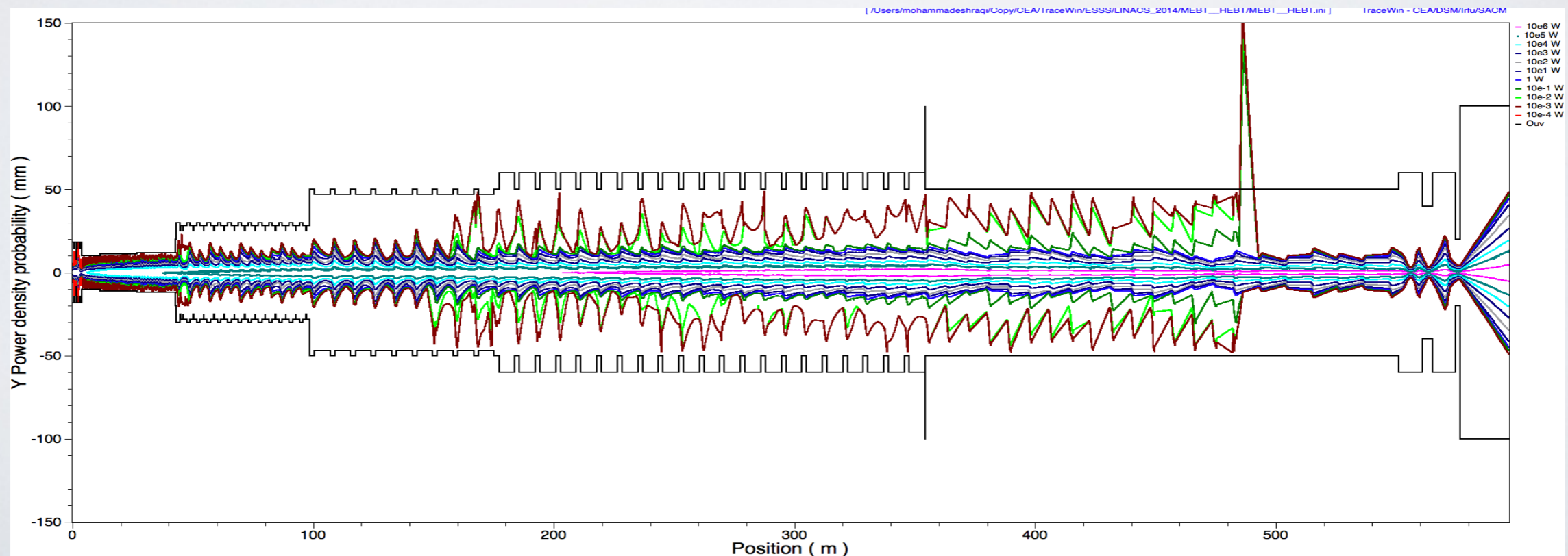
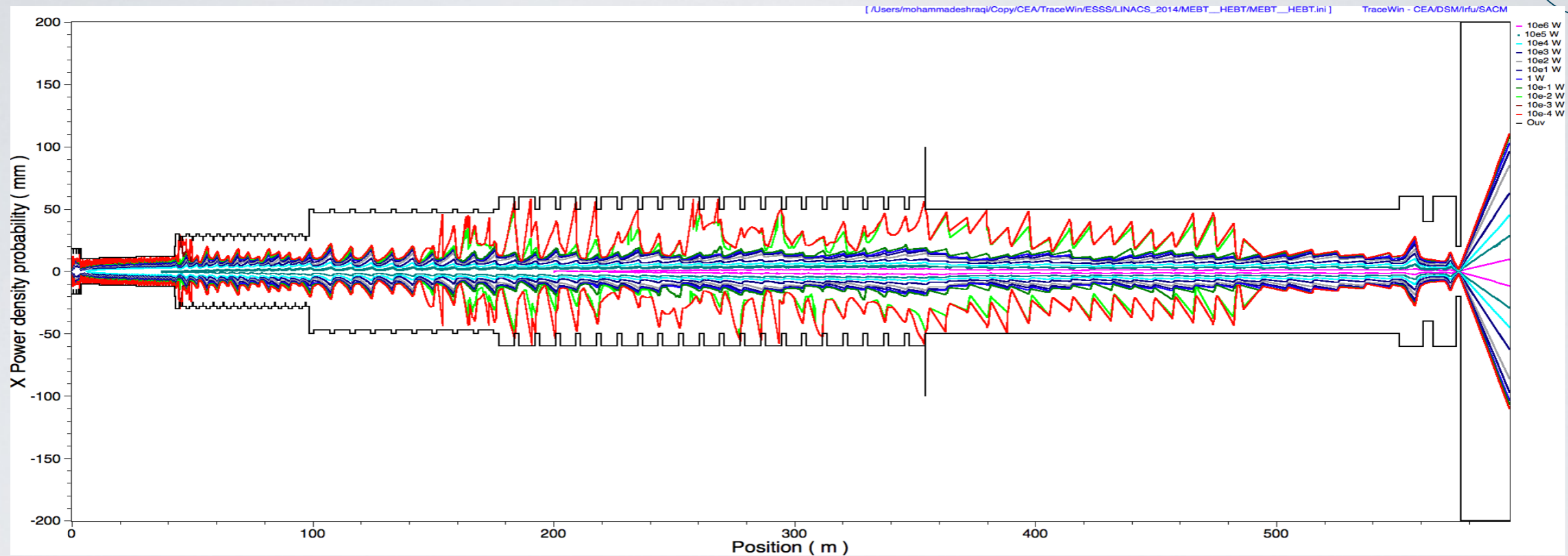


# RFQ TO END ERROR RESULTS I

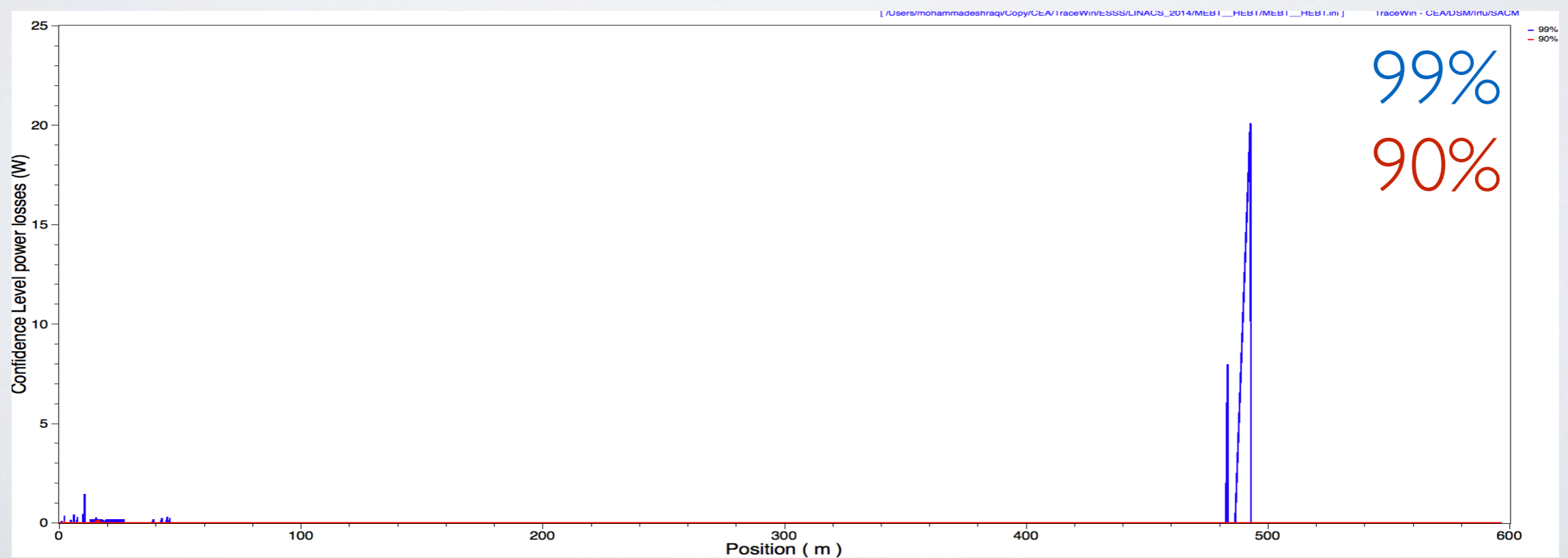
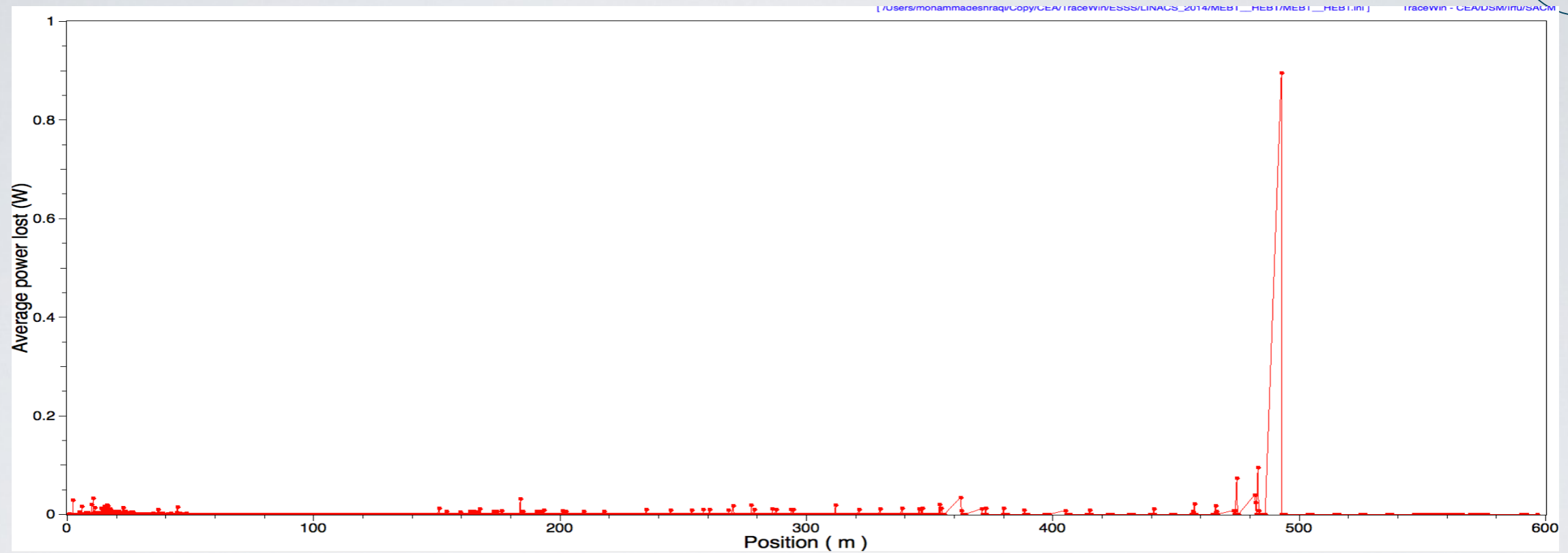
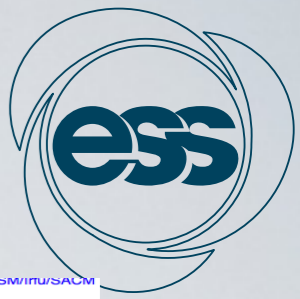


Thanks to Heine Dølrath Thomsen for early delivery of HEBT lattice

# RFQ TO END ERROR RESULTS II



# RFQ TO END ERROR LOSS MAPS





# SUMMARY

- The end to end runs have been performed using a gaussian beam truncated at 4 sigma, generated at the RFQ input.
- The same beam is used for end to end error studies.
- Individual error studies on all sections of the linac is finished and the tolerances are set.
- The end to end error studies show that the average losses is  $\sim 0.1$  W/m
- 99% of the simulated linacs show a loss level less than  $\sim 1$  W in each meter, with a single hot spot in the dogleg area
- The “right” position for collimators is a function of energy and depends on the shape of tails



THANK YOU FOR YOUR  
ATTENTION AND COMMENTS