

MXCuBE 3 web application: on the way to next generation experiment control

Mikel Eguiraun - mikel.eguiraun@maxiv.lu.se NOBUGS 16



Outline

- MXCuBE project
- MXCuBE v3
 - Technologies in use
 - User interface
 - Demo video
- Next steps & work force

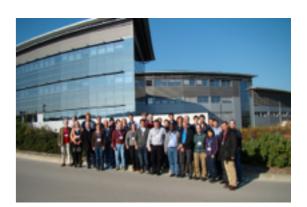




MXCuBE

- Macromolecular Xtallography Customized Beamline
 Environment
 - Started in 2005 at ESRF
 - Beamline control and data acquisition platform for running MX experiments

- Supported by the following partners: ESRF, Soleil, MAX IV, HZB, EMBL, Global Phasing Ltd, DESY, ALBA.
- Already tested software & builtin experience (many years + many people + many beamlines)



ALBA, Dec. 2015





3

MXCuBE - Main Features

- Customizable for each beamline/facility
- Reuse of existing code for different beamlines; common solution for users
 - same or similar hardware devices
 - same or similar experimental procedures
- Hardware mockups available, testing and developing without equipment
- Current stable version based on PyQT
- Hide the complexity of the Hardware to the user (and to the developers...) thanks to the usage of the **HardwareObjects**



MXCuBE - HardwareObjects

- Self-contained piece of software linking devices and graphical interface
 - Through the *HardwareRepository*
- Configured through xml files
- A HO is not only hardware! Procedures/sequences etc
- Emitting signals to hardware objects, graphical elements
- Supported protocols: Tango, EPCIS, Sardana...

class MicrodiffMotor(Device):

```
<device class="MicrodiffMotor">
<username>Omega</username>
<exporter_address>130.235.94.124:9001</exporter_address>
<motor_name>Omega</motor_name>
<unit>1e-3</unit>
</device>
MotorOmega.xml
def init(self):
self.position_attr = self.addChannel({"type":"exporter",
"name":"position" },
self.motor_name)
def getPosition(self):
return self.position_attr.getValue()
def move(self, absolutePosition)
self.position_attr.setValue(absolutePosition)
```



MicrodiffMotor.py

MXCuBE 3



- Beamline control and data acquisition as web application
- Reuse existing HardwareObjects maintaining compatibility with v2
- Modern web technologies for user interface
- Easier integration with LIMS (*laboratory information management system*)
- Maintenance and deployment (decoupling client/server)
- Remote access in a more *natural* way
- Feedback from user community

https://github.com/mxcube/mxcube3



MXCuBE 3: Current status

- Under development but first data collection during Biomax commissioning (June 2016, MAX IV)
- Sample imaging and operation
- Basic data collection strategies
 - experiment queue configuration and execution
 - standard dc, characterisation, helical
- Screen mirroring / master-slave operation
- LIMS and sample changer integration very advanced





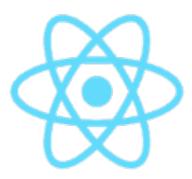
Backend

- Python **Flask** microwebframework:
 - web server made simple
 - extensions (database, login, ...)
 - easily adaptable to your needs while scalable
- http request **API**: rest-like
 - url for each function
 - Simple to add new features without changing existing ones
- Flask socketio for sending HO messages
 - server-client bi-directional communication, websocket based
- Reuse the existing Hardware Objects



Frontend REACT

- User interface has been redesigned (compared to MXCuBE v2)
- Javascript/React library (Facebook)
- Only for the user interface (the V in MVC)
- UI is described as a collection of components
 - Different components programmed independently
- Reusing existing code when the layout changes





Frontend REDUX

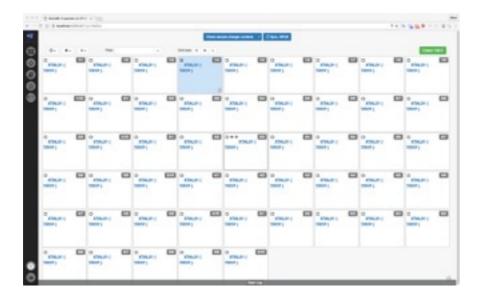
- **Redux** application architecture/pattern
 - Predictable state container for JavaScript apps
 - Changes on the internal state in a single place
 - Unidirectional data flow
 - Clear and safe development

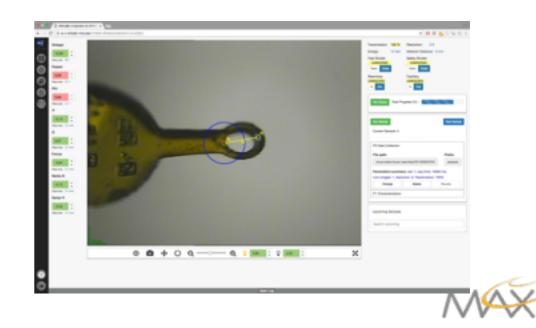




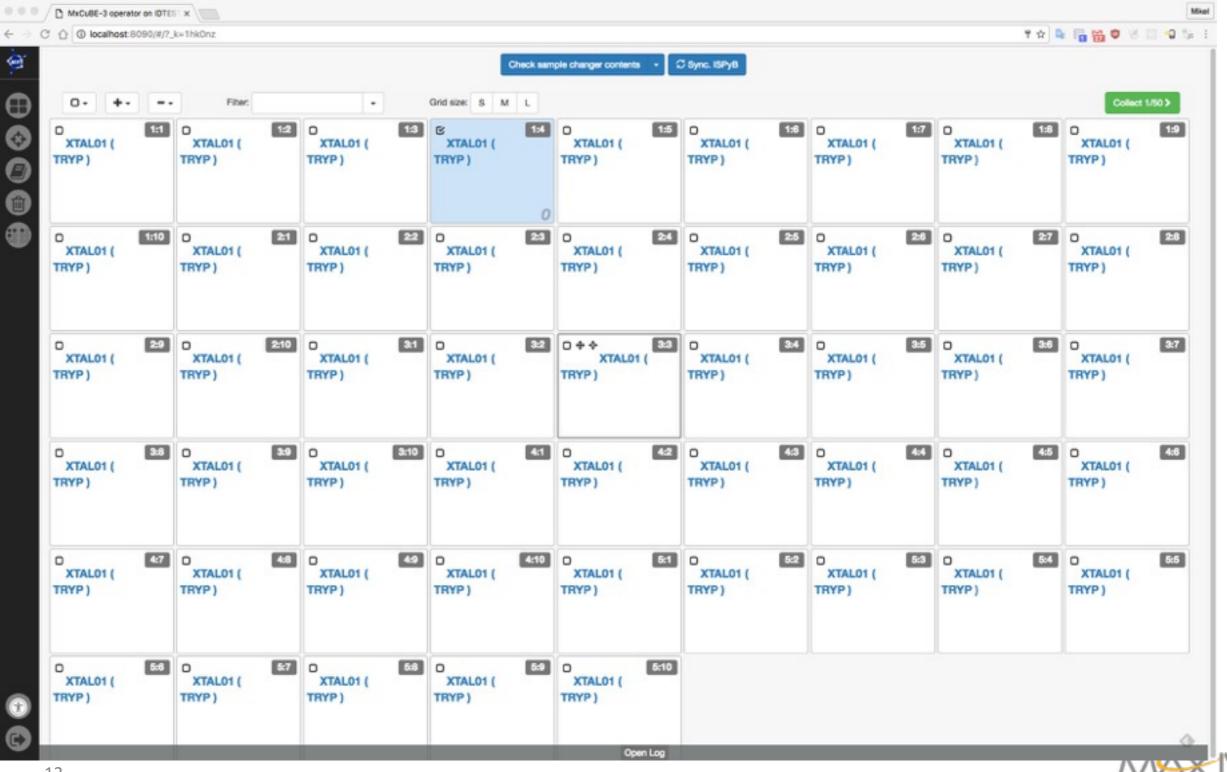
User Interface

- Two main operation modes:
 - Automatic:
 - multiple sample selection and configuration
 - Workflows (predefined sequence of automatic operations)
 - Manual:
 - sample by sample
 - manual operation and configuration



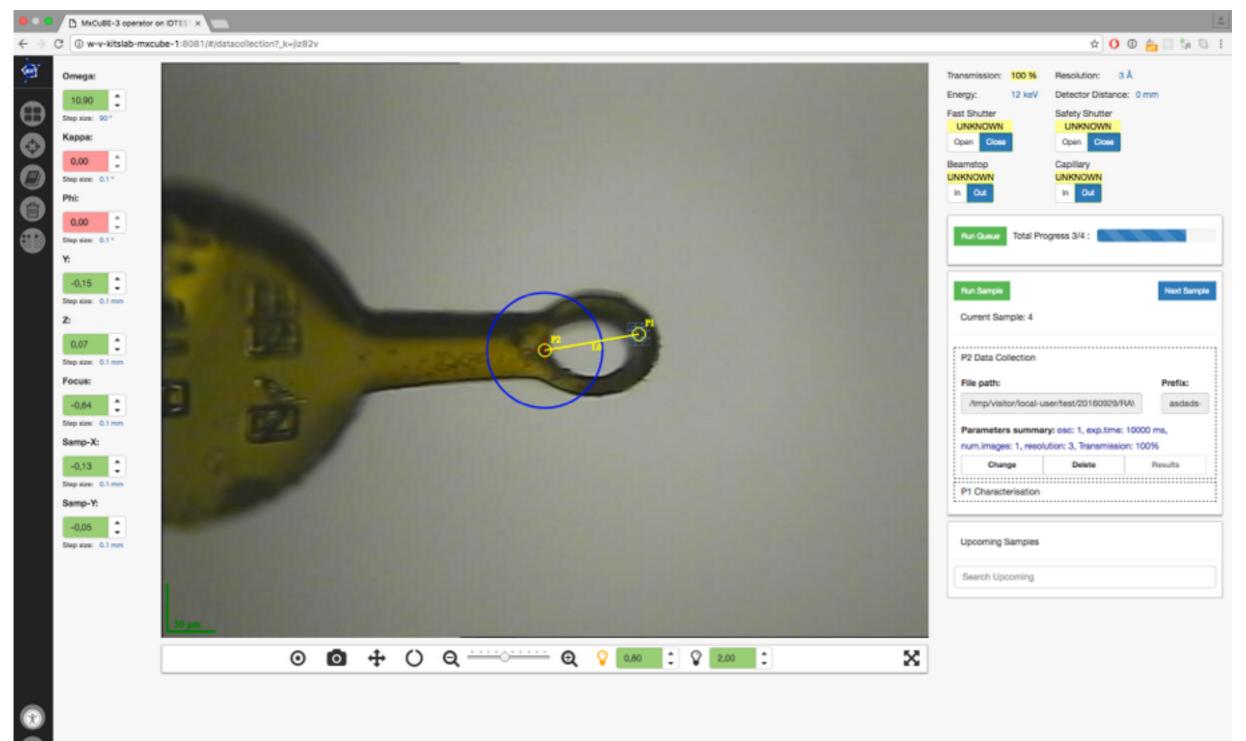


Sample Grid



12

Data Collection



2

13

100

Demo video

		n 🖇 🗉 🕙 🗢 69% 配 Mon 3 Oct 10:15 Mikel Eguiraun Q 1
O macube/macube3: MXCuBE 3 × MxCuBE-3 operator on IDTES ×		
C 🛆 O localhost:8090/#/login?_k=whxu04		१ फ्रे 📴 📬 🧐 🐨 🕤 🖏
	(MX)	
	Welcome to MX Beamline at MAXIV	
	LoginID	
	User	
	Password	
	Password	
	Circo In	
	Sign in	

Next steps

- Continue the development
 - Finish LIMS and sample changer interfaces
 - Polish the interface (icons, buttons, minimal layout changes)
 - Debugging
 - Performance improvements
 - Additional views
 - Ready for users



MXCuBE3 People

MAX IV: M. Eguiraun, A. Milan-Otero, J. Nan, F. Bolmsten, M. Thunnissen, V. Hardion, D. Spruce
ESRF: M. Guijarro, M. Orkarsson, A. Beteva, D. de Sanctis, G. Leonard, J. Meyer, A. Gotz

Supported by: MXCuBE collaboration MAX IV MX and KITS teams ESRF BCU and SB teams



Thanks for your attention!



