Beam diagnostics
for particle accelerators

Maja Olvegård
Uppsala University

Nordic Particle Accelerator School
Lund, August 19, 2015
Outline

• Why?
  – Why do we need it?

• What?
  – What types of beam diagnostics?

• How?
  – Which methods do we use to diagnose the beam?

• Where?
  – Where do we place our diagnostics?
Why do we need beam diagnostics?

- Accelerators have a function:
  - Produce radiation, neutrons, etc
  - Produce exotic particles through beam-beam or beam-target collisions
  - Irradiate cancer tumors, food, etc

- We need to know that we do this in the desired way:
  - Optimizing:
    - Optimize radiated light (intensity, wavelength, geometric precision, stability,...)
    - Maximize number of particles produced (luminosity)
  - SAFETY:
    - Protect people
    - Protect target
    - Protect machinery (protect the accelerator from itself)

- The beam is small, sometimes dangerous and we cannot directly “see” it.
  - We need detectors, equipment with the task to monitor all the properties of a particle beam that affects the operation of the accelerator.
Diagnostics or instrumentation?

- Sometimes we use *instrumentation* to refer to the detectors or instruments that measure or monitor beam properties while *diagnostics* is the method itself.

- Note that some parameters in accelerator physics is a property of the accelerator lattice (dispersion, chromaticity).

- Other are properties of the beam. (energy, emittance, bunch length ?)

- Most of them are an effect of the whole machine and its operation.

Which parameters and properties are we interested in?
Let us think together....

Beam

- Transverse distribution
- Transverse size/shape
- Transverse divergence
- Loss
- Emittance
- Position
- Intensity
- # particles/s
- Current
- Mean energy
- Energy distribution
- Energy spread
- Longitudinal distribution
- Time structure
- Arrival time
- Bunch length/shape
- Arrival time
Beam structure

pulse or bunch train

\[ t_p \]

pulse or machine repetition rate

\[ f_{rep} = \frac{1}{T_{rep}} \]

bunch repetition rate

\[ f_b = \frac{1}{T_b} \]
The beam

cross section or projection

transverse cross section or projection

direction or angle

horizontal emittance \( \varepsilon_x \)

transverse phase space

longitudinal distribution

momentum distribution

Nordic Particle Accelerator School: Beam Diagnostics
How do we diagnose the beam?

- Vast variety of accelerators with different purposes and therefore different needs.
- Beam parameters vary greatly, so must the techniques to diagnose these parameters.
- A few central concepts:

  parasitic □ □ destructive
  single-shot □ □ multi-shot
  continuous operation □ □ dead time
  integrated measurement □ □ slice measurement
  absolute □ □ relative

  ... and radiation hardness.

  e.g. time resolved?
  cross-calibrate with other instrument?
How can we “see” the beam?

- We have to use the fundamental forces of nature.
- Always charged particles $\rightarrow$ surrounded by an electromagnetic field
  - We can sense this field in several different ways
  - Indirectly (placing something near the beam)
  - Directly (placing something in the way of the beam)
“Sensing” a particle beam

Charged particles surrounded by an electric field. Field around a point charge:

- At rest
- Moving
- Moving at relativistic speed

The beam pipe shields the surroundings from this field.
Synchrotron radiation

A charged particle will if accelerated emit energy in form of *synchrotron radiation* (described by classical electrodynamics). For relativistic particles it can be a substantial amount of energy if the acceleration is perpendicular to the direction of motion.

Radiated power: \[ P \propto \frac{\gamma^4}{R^2} \]

\[ \gamma = \frac{1}{\sqrt{1 - v^2/c^2}} \]

\[ R \] radius of curvature

Note: Details of synchrotron radiation will be presented by Sverker Werin on Friday.
Beam current
The Faraday cup is a metallic body in which the beam particles are stopped. Every absorbed charge is sensed as an electric signal from the cup. Naturally, the cup must be long enough to stop all primary and secondary particles. It must be able to stand the thermal power that the beam induces.

A “bias voltage” $V$ can force backscattered particles back into the cup.
The beam pipe shields the surroundings from this field.

\[ E \quad \beta c \quad \text{conductive vacuum pipe} \]

\[ \text{vacuum pipe} \quad \text{ceramic gap} \]

\[ I_{\text{wall}} \rightarrow \quad \text{parasitic} \]

\[ I_{\text{beam}} \rightarrow \]

M. Olvegård, August 2015

Nordic Particle Accelerator School: Beam Diagnostics
We interrupt the conductive wall (beam pipe) by inserting a ceramic gap. The wall current will take any available path past this gap. In this case the wall current will propagate through the resistor. We then measure a voltage drop over the resistor. Normally works best at low frequencies, that is slow changes in the beam current. Careful consideration of all capacitances present is needed, together with the impedance added to the beam environment.
Current transformer

- The “right hand rule”:
  - Insert a torus to guide the magnetic field generated by the beam
  - Current windings will “pick up” the field, which is proportional to the beam current.

A real one, commercially available:
Beam Position Monitors

- BPM -
“Buttons” to pick up electric charges induces by the passing beam.
Non-linear, requires very careful calibration.
If properly calibrated, can be used for beam current measurements as well.
Used when the bunch length ≈ bpm length, e.g. in synchrotron light sources

Horizontal position
\[ x = k_x \frac{(A + D) - (B + C)}{A + B + C + D} \]

Vertical position
\[ y = k_y \frac{(A + B) - (C + D)}{A + B + C + D} \]
● When the bunch passes through the cavity it excites an electromagnetic field in the cavity.
● If the beam passes through exactly in the center there will be no field.
● The further away from the axis, the stronger the field.
● Very sensitive, but complex to make. Used mostly for electron linacs (short bunches).
Other BPM types

**Shoe-box**
Large plates as electrodes – useful for low currents.

**Strip-line**
Used for very short bunches and for beams traveling in opposite direction.

---

In common for all BPMs is the importance of signal handling and data acquisition electronics; bandwidth, impedance matching, amplifier and filter choice, etc.
Transverse profile
Screen

beam

screen

optical system to guide light

camera

perturbing
Types of screens

- (Optical) Transition Radiation (OTR)
  - the beam polarizes the screen material
  - screen emits light when the polarization is “relaxed”
  - intensity increases with particle energy
  - almost instantaneous – can be used for fast measurements

- Scintillating screen:
  - atomic excitations
  - lots of light
  - slow process


First beam in the LHC
Examples of screens

- Scintillating screen in the LHC dump line
- Screen for emittance measurement at CTF3

Nordic Particle Accelerator School: Beam Diagnostics

M. Olvegård, August 2015
• Scan a wire through the beam.
• Beam particles hit the wire and secondary particles are emitted.
• The secondary emission is detected as a current.
• Also possible to use a laser beam as a wire.
SEM grid

- Instead of one moving wire, a grid of wires to detect secondary emission from beam particle hits: Secondary Emission Grids (SEM-grid) or Harp
Beam energy and momentum
The curvature of the path in a magnetic field depends on the particle momentum $p$:

$$p = \frac{q}{\alpha} \int B \, dl$$

The Lorentz force:

$$\vec{F} = q\vec{v} \times \vec{B}$$

relativistic:

$$\gamma \frac{d\vec{p}}{dt} = \frac{q}{m_0} \vec{p} \times \vec{B}$$
A BPM in the spectrometer line gives the central momentum of the beam accurately.

A profile monitor (screen, grid, multi-array Faraday cups ...) gives the momentum distribution of the beam.

Remember:
- The intrinsic size of the beam in the bending plane must be small compared to the beam size due to the momentum spread.
- The accuracy of the momentum measurement is determined by how well we know the integrated field of the magnet.
Time-of-flight TOF

- Measure time of flight from A to B: \[ T_{tof} = t_B - t_A = \frac{L}{v} \]
- Calculate kinetic energy: \[ E_k = \frac{mv^2}{2} \]

Intuitive, BUT:

- For relativistic particles \( v \rightarrow c \) which means that the speed is the same even if the energy is different.
  - It becomes impossible to measure such short time differences.
- So, only used for heavy particles at low energy.
Longitudinal distribution & Bunch length
Longitudinal profile

- Particle bunches can vary from .... to ....
  - LHC: $0.27 \text{ ns} \rightarrow 8 \text{ cm}$
  - ESS (end): $3 \text{ ps} \rightarrow 1 \text{ mm}$
  - MAX IV: down to $31 \text{ fs} \rightarrow 10 \mu\text{m}$

- Long bunches can be measured with a fast current transformer.

- Very short bunches need special tricks.
Bunch length: a) sweep particles

- A transversely deflecting cavity transfers the temporal density to vertical density on a screen.
An OTR screen generates a light “bunch” or pulse corresponding to the particle bunch duration. The photon pulse is transformed to a new electron bunch at low energy, which is swept across a screen using a ramped field.
A short laser pulse is shone through a birefringent crystal. The laser light is initially blocked by two polarizing plates at 90 degrees. A particle bunch approaches with its surrounding electric field strongly boosted to a transverse disk. The electric field polarizes the crystal and in that way, changes the refringence properties of the crystal.
The laser light that is passing through the crystal changes polarization due to the presence of the electric field. Now the cancellation is no longer complete and some light is transmitted through the second polarizer plate. This light is directed to a grating, which splits the light up according to wavelength. A camera can then pick up the light intensity variations with wavelength. Remember: the time variable is encoded in the wavelength. Now the particle density is encoded in the light intensity.
A diagnostic:

Emittance measurement
Emittance measurements

- Three parameters that define the beam (transversely):
  - width, divergence and coupling of the two.

- Three parameters to be measured, for example:
  - beam width at the waist.
  - beam width away from waist.
  - position of waist.
Quadrupole scan

- Measure the beam size $w_1$ behind a quadrupole with setting $f_1$. 
Quadrupole scan

- Measure the beam size $w_1$ behind a quadrupole with setting $f_1$.
- Change the quadrupole setting and measure the beam size again.
• Measure the beam size $w_1$ behind a quadrupole with setting $f_1$.
• Change the quadrupole setting and measure the beam size again.
• Repeat until you have at least three measurements. With the transfer matrix known you now have enough information to extract the incoming beam parameters.
Emittance measurements

There are other methods to determine the emittance:

- **Slit-and-grid** (1D, multi-shot)
  - Diagram showing a slit and grid or screen.

- **“pepper pot”** (2D, single shot)
  - Diagram showing a pepper pot and grid or screen.

- **Multiple screens**
  - Diagram showing an array of screens labeled A, B, C, ..., for beam diagnostics.
There are many more out there...

- Residual gas monitor (transverse profile)
- Optical diffraction radiation (transverse and longitudinal size)
- Synchrotron light monitor (transverse and longitudinal profile)
- Mercury jet monitor (profile)
- Cherenkov radiation monitor (various)
- Feschenko monitor (bunch shape)
- Shintake monitor (nm scale beam size)
- Microchannel plate, MCP (transverse profile)
- Ionization chamber (beam loss)
- Solid-state Ion chamber, PIN photodiode (beam loss)
- Scintillation counters (beam loss)
- ...

M. Olvegård, August 2015
Measurement & Instrument Quality
Measurement & Instrument Quality

- Trueness
- Precision
- Accuracy
- Uncertainty
- Resolution
- Dynamic range
- Systematic error
- Random error
It is preferable to talk about the uncertainty connected to a measurement value. Errors should be corrected.
Measurement & Instrument Quality

**resolution** — the **fineness** to which an instrument can be read.

**precision** — the **fineness** to which an instrument can be read **repeatably and reliably**.

**accuracy** — the **correctness** of a measurement value. **trueness**

Read more: [https://en.wikipedia.org/wiki/Accuracy_and_precision](https://en.wikipedia.org/wiki/Accuracy_and_precision)
Precision Vs. Accuracy

- Precision: Calibration improves precision.
- Accuracy: True value improves accuracy.

- Precision: Data points improve precision.
- Accuracy: True value improves accuracy.

M. Olvegård, August 2015
Nordic Particle Accelerator School: Beam Diagnostics
Instrument Performance

Which ruler measures best?

accuracy
resolution
dynamic range

Which ruler measures best?

M. Olvegård, August 2015
Nordic Particle Accelerator School: Beam Diagnostics
Example

So, which ruler measures best??
Example: BPM

DEVELOPMENT OF NANOMETER RESOLUTION RF-BPMs

T. Shintake
KEK: High Energy Accelerator Research Organization
1-1 Oho, Tsukuba, Ibaraki, 305 Japan

Abstract:
The future e+e- linear colliders will use high resolution and high accuracy BPMs. A highest resolution of 10 nm is required for the beam-based alignment of magnetic elements in the final focus system. Very tight zero-point center accuracy, in the range of 1 to 10 μm, is required to align the accelerating structures in the main linac. The cavity type RF-BPM (Radio Frequency Beam Position Monitor) is one of the best candidates to meet those demands.

This paper describes a brief history of high resolution RF-BPM development, the beam test of C-band BPM at FFTB beam line, analytical models of resolution and accuracy in a simple pillbox-cavity BPM.

1. Introduction
Future linear colliders [1] will require high performance BPMs to control the beam trajectory with high precision in order to maintain a stable collision of required.

Among various type of BPMs, such as the electrostatic BPM using four button-pickups or the stripline type BPM, only the cavity RF-BPM has a potentiality to achieve the resolution of nm range and the center accuracy of μm level.

According to the accelerating structure alignment, there is another scheme, which is under development at NLC project. The wakefield power induced in the accelerating structure will provide direct information of the cavity displacement from the beam. The TM110 mode in the accelerating structure can be to detect the beam position. This idea is so called the structure BPM, which is planed to be used in the NLC design and its powerfulness was demonstrated with beam in ASSET test [4]. Since the basic mechanism in this scheme is exactly same as that in the cavity RF-BPM, we will focus our discussions into the cavity RF-BPM in this paper.
Summary

- Beam instrumentation (detector) and diagnostics (method) are necessary to
  - understand and control the accelerator
  - protect people and equipment
- Each machine has its requirements depending on
  - beam intensity
  - beam size,
  - beam energy and power
  - time structure
  - availability...
A few final words

An accelerator can never be better than the instruments measuring its performance!

- Beam instrumentation specialists get to combine their knowledge from many areas of physics:
  - particle and beam physics, detector physics and technology, electromagnetism, material science
  - electronics, mechanics, computing, numerical analysis, signal processing
  - ...and much more!

- So, it's a fun, challenging and important field to be in!
“To think right is great, but to measure right is greater”

Motto of the High Energy Physics Division at Uppsala University

Free adaptation of Uppsala University’s motto:

“To think free is great, but to think right is greater”

(Thomas Thorild, 1794)
Literature


- The U.S. Particle Accelerator School (USPAS)
  - USPAS on Accelerator and Beam Diagnostics, University of New Mexico, June 2009

- The CERN accelerator school (CAS)
  - CAS 2008 on Beam Diagnostics:
    - CERN Yellow Report: CERN-2009-005
  - CAS 2003 on General Accelerator Physics
    - CERN Yellow Report: CERN-2006-002
Extra slides
Quadrupole scan

- Assume a section of an accelerator with a beam size monitor behind at least one quadrupole magnet. We assume that the transfer matrix $R$ from the (first) quadrupole to the monitor is known.

- Remember that the sigma matrix is defined as

\[
\bar{\sigma} = \begin{pmatrix} \sigma_{11} & \sigma_{12} \\ \sigma_{12} & \sigma_{22} \end{pmatrix} = \varepsilon \begin{pmatrix} \beta & -\alpha \\ -\alpha & \gamma \end{pmatrix} = \begin{pmatrix} \langle x^2 \rangle \\ \langle xx' \rangle \\ \langle xx' \rangle \\ \langle x'^2 \rangle \end{pmatrix}
\]

- The sigma matrix is transported from A to B using $R$:

\[
\bar{\sigma}_B = R \bar{\sigma}_A R^T \quad \text{with} \quad R = \begin{pmatrix} R_{11} & R_{12} \\ R_{21} & R_{22} \end{pmatrix}
\]

- Let's assume an incoming beam defined by the sigma matrix above and let be the beam size on the screen. We can expand the matrix equation \( \star \).
Quadrupole scan, cont. a)

- ... and express the beam size on the screen as

\[ w^2 = \sigma_{11} R_{11}^2 + \sigma_{12} R_{11} R_{12} + \sigma_2 R_{12}^2 \]

- For every quadrupole setting \( f_i \), a new beam size \( w_i \):

\[ w_i^2 = \sigma_{11} R_{11}^2(f_i) + \sigma_{12} R_{11}(f_i) R_{12}(f_i) + \sigma_2 R_{12}^2(f_i) \]

- We repeat the measurement and obtain a system of equations

\[
\begin{pmatrix}
  w_1^2 \\
  w_2^2 \\
  \vdots \\
  w_n^2
\end{pmatrix}
= 
\begin{pmatrix}
  R_{11}^2(f_1) & R_{11}(f_1) R_{12}(f_1) & R_{22}^2(f_1) \\
  R_{11}^2(f_2) & R_{11}(f_2) R_{12}(f_2) & R_{22}^2(f_2) \\
  \vdots & \vdots & \vdots \\
  R_{11}^2(f_n) & R_{11}(f_n) R_{12}(f_n) & R_{22}^2(f_n)
\end{pmatrix}
\begin{pmatrix}
  \sigma_{11} \\
  \sigma_{12} \\
  \sigma_{22}
\end{pmatrix}
\]
Quadrupole scan, cont. b)

- We now have the matrix equation \( \bar{u} = A \bar{v} \) which we want to solve for \( \bar{v} \).
- In the least-squares sense we have \( \bar{v} = (A^T A)^{-1} A^T \bar{u} \).
- Finally, we extract the Twiss parameters from \( \bar{u} = \begin{pmatrix} \sigma_{11} \\ \sigma_{12} \\ \sigma_{22} \end{pmatrix} \):

\[
\varepsilon = \sqrt{\text{det}(\sigma)} = \sqrt{\sigma_{11}\sigma_{22} - \sigma_{12}^2} \quad \beta = \sigma_{11}/\varepsilon \quad \alpha = -\sigma_{12}/\varepsilon
\]
Example: Diagnostics sector

An accelerator sector where many parameters can be measured together:

- Beam position and current with a BPM
- Transverse emittance and Twiss parameters through a quadrupole scan and a screen
- High resolution (average) and Time-resolved momentum profile with a screen and a multi-array Faraday cup in a spectrometer line
- In addition, together with a streak camera the emittance screen can be used for bunch length measurements.

The layout is taken from the Compact Linear Collider Test Facility at CERN.