

Chopper Integration Controller (CHIC) & CHIC- EPICS integration

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Introduction



Situation

- ESS instruments will have complex chopper systems
- >140 chopper axis at facility
- Facility wide integrated control system (ICS)





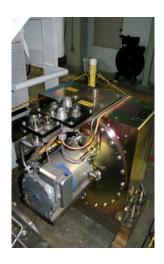


Challenge

Integrate chopper drives from multiple suppliers with the facility

Goal is to ensure:

- Performance
- Reliability
- Maintainability
- Cost







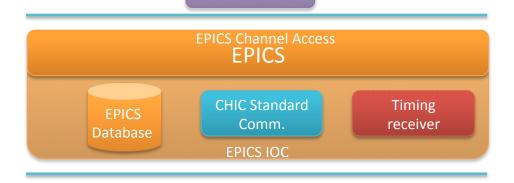


Chopper Integration Controller (CHIC)



Chopper Control System

- Four layers
 - DMSC HMI for users
 - EPICS
 - Facility wide control network
 - EPICS IOC
 - Timing receiver
 - CHIC Chopper integration controller
 - Chopper drive and support equipment



CHIC

DMSC

НМІ

Chopper Drive (N)

Motor & Bearing Emergency Stop
Drive Input

Sensors Clock Signal Input



CHIC Functions

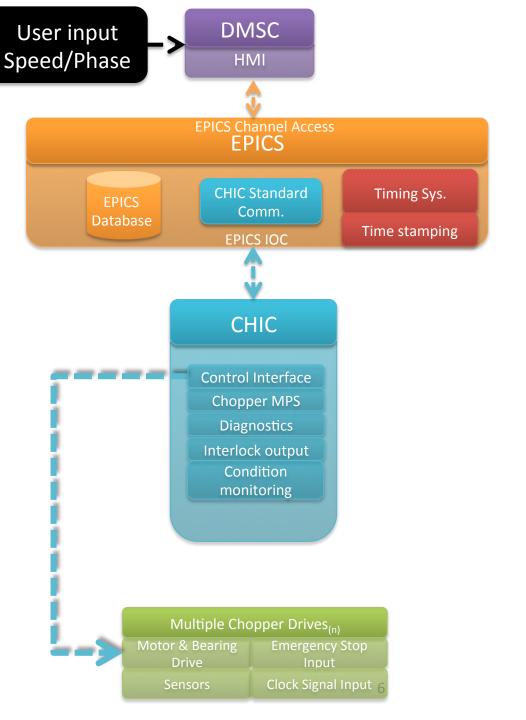
- Control Interface
 - Standard interface between EPICS and chopper drives
 - Same interface and GUI for all drives
- Chopper MPS
 - Vacuum, Cooling, UPS,
 Vibrations
- Diagnostics
 - Readout from drives
 - Motor temp, currents, alarms
- Interlock output
 - E.g loss of vacuum, cooling, power
- Condition monitoring
 - Predictive maintenance
 - Monitors changes and trends



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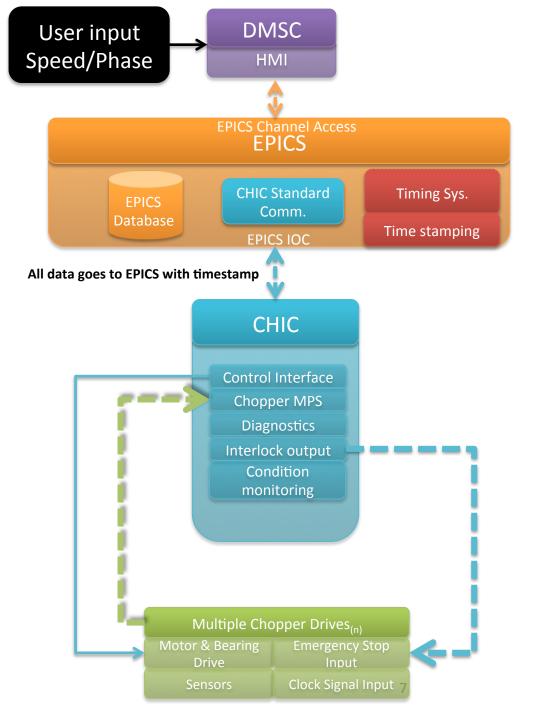
Communication Structure

- User inputs speed/phase
- EPICS sends the command to CHIC.
- CHIC is sending a supplier specific commands to the drives



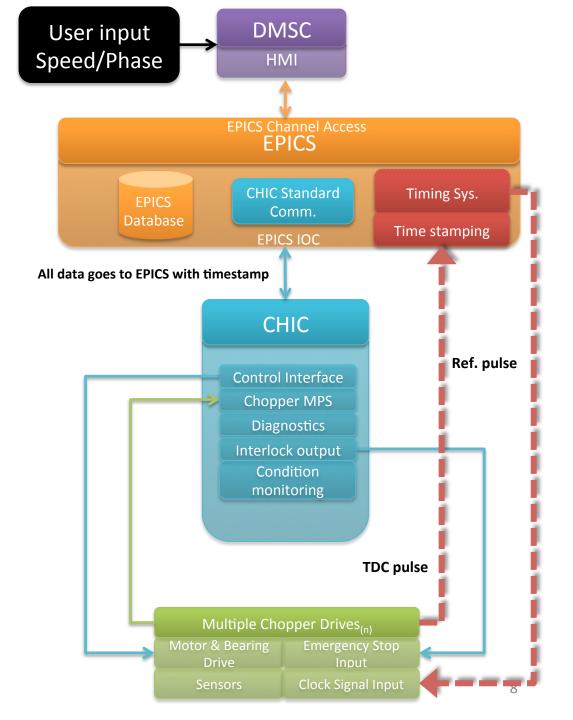
Communication Structure

- Readout from chopper drives
 - Motor temp, motor currents, error messages etc.
 - Monitoring
- Chopper MPS
 - External system, vacuum,
 UPS, cooling, vibrations.
- Interlock signal
 - Stopping the Chopper



Communication Structure

- Veto at DMSC level
- Phase error is determined with Ref pulse and TDC pulse
- All chopper drives will receive the pulse simultaneously

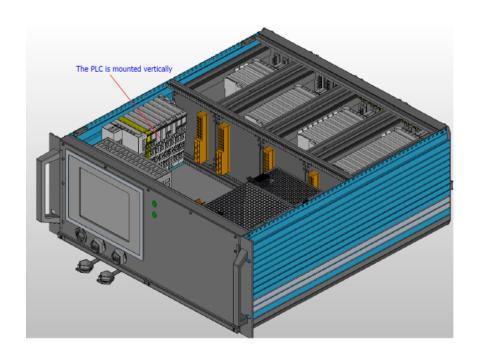


CHIC Hardware



CHIC Crate

- Designed for 19" rack
- Beckhoff PLC
- 24V Power supply
- Customized I/O modules
- LCD screen



Early version of the CHIC crate

CHIC Benefits



- Standardized interface to EPICS for all chopper suppliers
- One GUI for all suppliers
- Unified error handling
- Monitoring system can be embedded in the CHIC



Chopper control rack





- Variant of the ESS standard instrument rack
 - Designed according to ESS standards and SE legislation.
- Modular design
 - Cooling unit (water- air)
 - Power distribution panel
 - CHIC
 - Chopper drives (≤ 4 / rack)
 - Timing receiver card
 - ICS Control box EPICS
 - UPS
- Adoptable to fit all the established chopper suppliers
- Protoype in the poster session



Prototype chopper control rack

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Prototype chopper control rack



CHIC-EPICS integration (ESSIIP)

Andres Quintanilla Mechatronics Engineer

ESSIIP

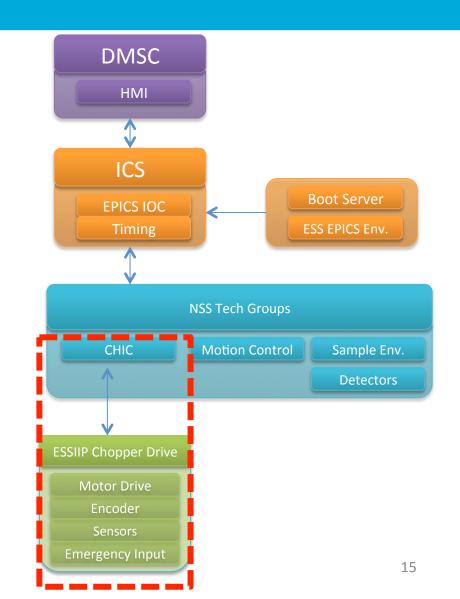


ESS Instrument Integration Project

- Technology development
- Evaluate integration strategies for ESS instrument control software & Hardware
- Testbed for different version of the CHIC

Main ESS stakeholders

- DMSC
- ICS
- NSS technology groups



ESSIIP



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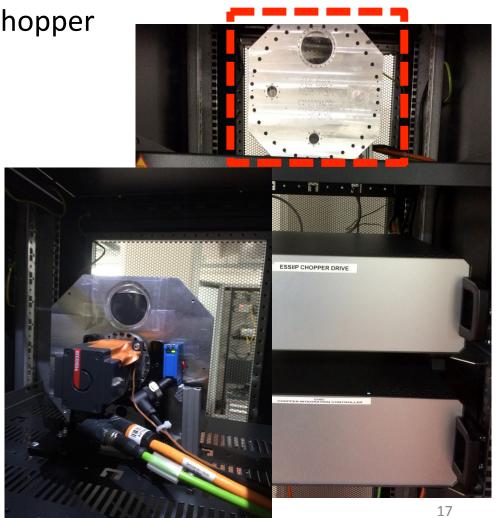


ESSIIP Chopper Mechanics



Quarter scale model of the ESS chopper tested at EMBLA

- Servo motor with resolver
- 200 mm Aluminum Disc
- Aluminum Housing
- Temperature sensor
- Optical sensor



ESSIIP Chopper Drive



- The Drive simulates the behaviour of a ball bearing chopper.
- Main Functionalities:
 - Set speed
 - Phasing of disc
 - Change direction of rotation
 - Parking functionality
 - Emergency Stop functionality
 - Diagnostics



CHIC



Controls the commands being sent to the drive

- Controlled transitions with Finite-state Machine logic
- Exposes all data with a standardized structure (error handling, commands, limits, etc).
- Feedback if a command was executed or not
- Communication diagnostics
- Calibration Parameters(Thresholds)

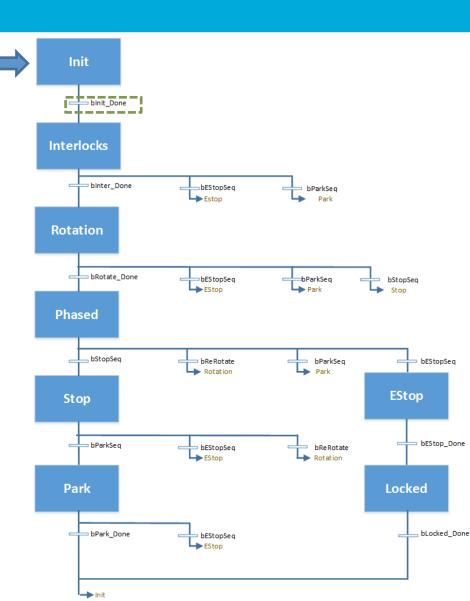






Initialization:

- Enables/powers the Drive
- Transition occurs when Drive and motor are powered.

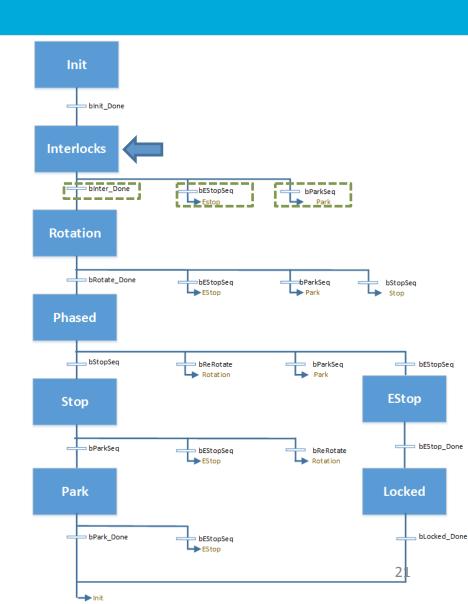






Interlocks:

- Checks all critical variables(Interlocksthresholds) in order to allow rotation
- Transition can go to:
 - Rotate
 - Emergency Stop
 - Park

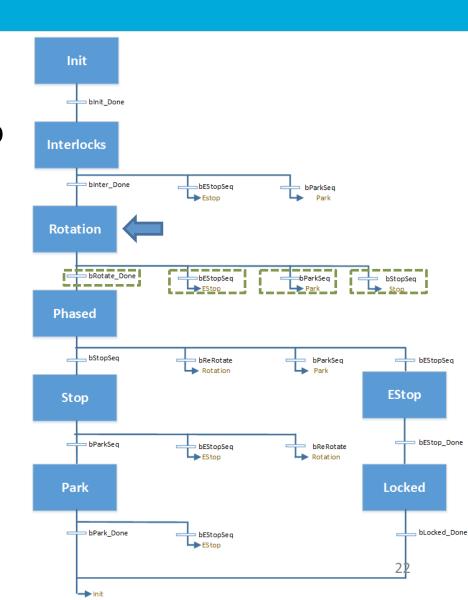






Rotation:

- Controls the commands to be sent in order to rotate in a safe way
- Transition can go to:
 - Phased
 - Emergency Stop
 - Park
 - Stop

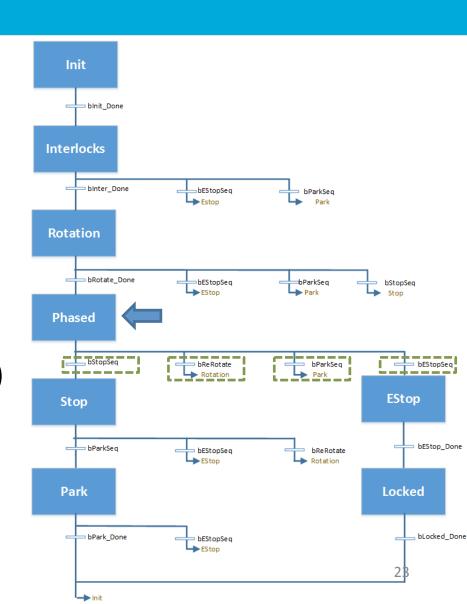






Phased:

- Keeps track of the time that has been in phase lock.
- Transition can go to:
 - Stop
 - Re rotate (new parameters)
 - Park
 - Emergency Stop

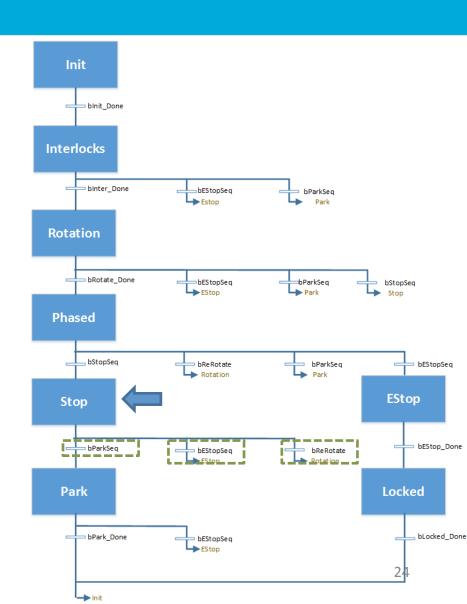






Stop:

- Stops the rotation with a low deceleration rate to reduce electrical and mechanical stress
- Transition can go to:
 - Park
 - Re Rotate
 - Emergency Stop

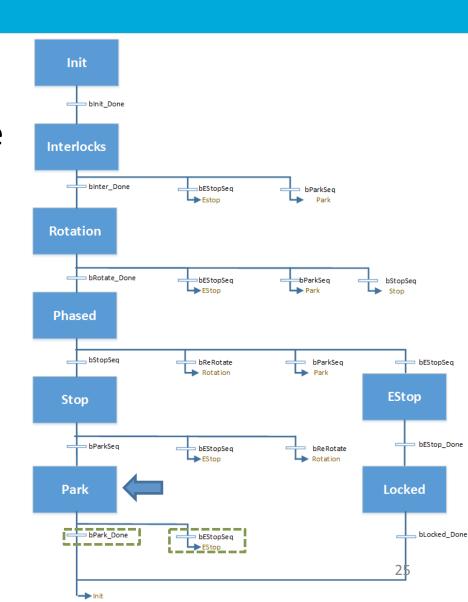






Park:

- It will move the disc to the Park setpoint, normally is the open position.
- Transition can go to:
 - Init
 - Emergency Stop

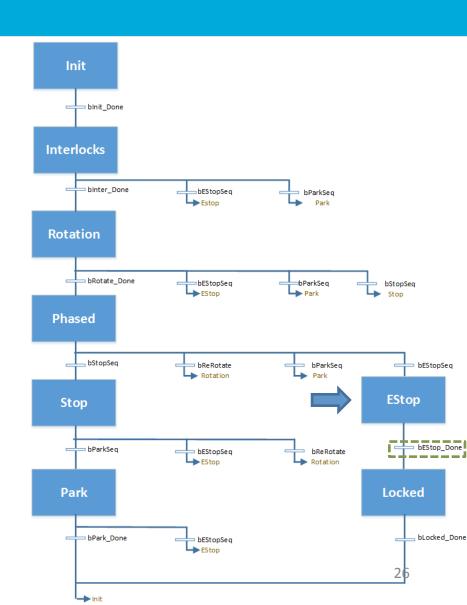






EStop:

- "Emergency stop" can be accessed from any state
- It will stop the rotation with the maximum deceleration rate allowed by the chopper.
- Transition can go to:
 - Locked

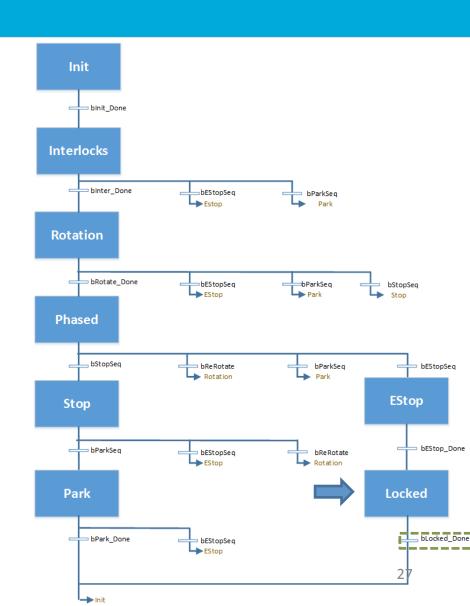






Locked:

- Blocks all commands and rotation in the chopper
- It makes possible to identify that last stop was by an Emergency and Mechanical/ Electrical parts should be inspected.
- Transition to init only happens after the state is acknowledge by user/operator





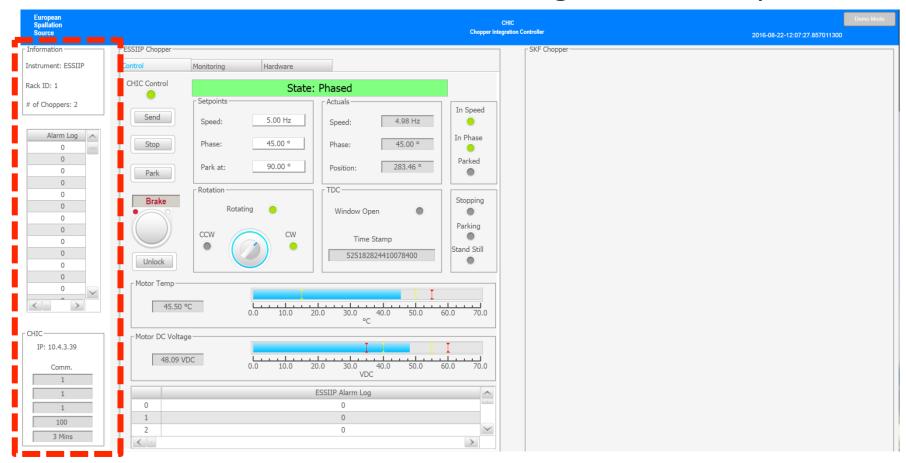
Interface V1

- Inside the CHIC PLC
- Accessible from the CHIC touch screen or html address.
- For testing purposes of the integration of suppliers



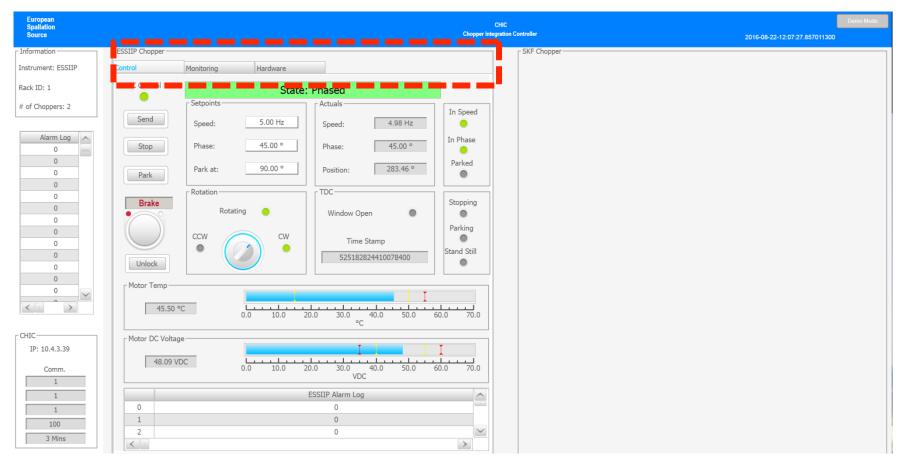


CHIC Interface V1: General alarm log in fixed left panel





CHIC Interface V1: Tab control



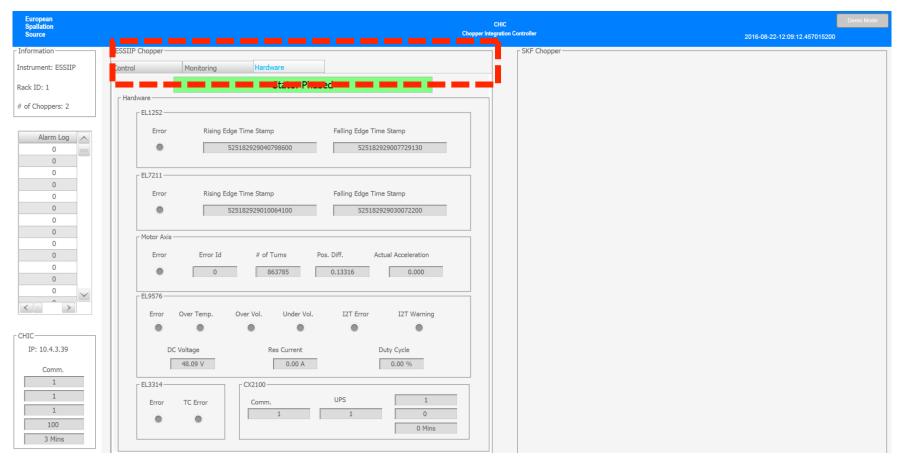


CHIC Interface V1: Tab control





CHIC Interface V1: Tab control





CHIC Interface V1: Park functionality



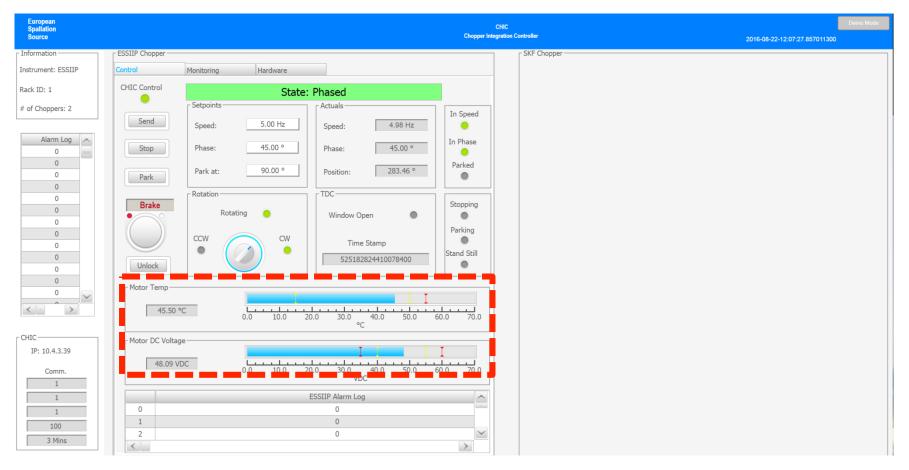


CHIC Interface V1: Emergency stop





CHIC Interface V1: Thresholds



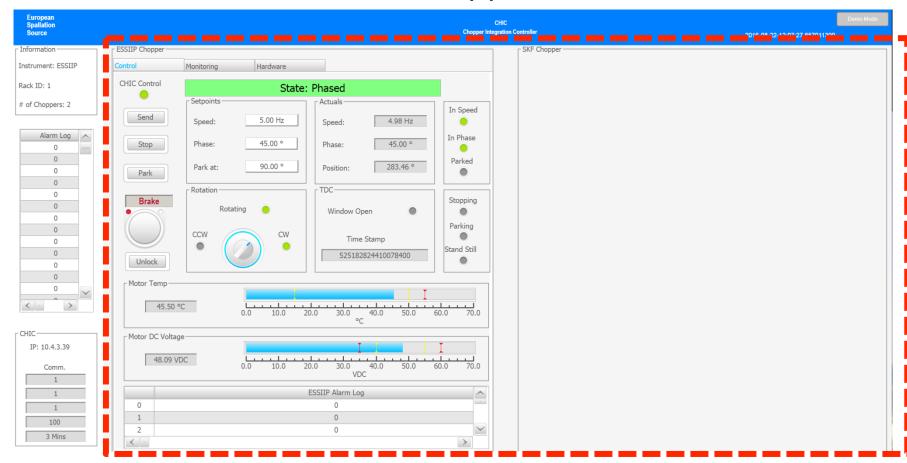


CHIC Interface V1: Detailed chopper Alarm log





CHIC Interface V1: Several choppers







 Friday 19th of August, first command was sent from Nicos, passing through EPICS IOC, then to the CHIC and eventually the chopper was rotating.





Questions?